

# Linear least-squares problem

Note Title

2024-09-27

Given

$$v_1, v_2, \dots, v_n \in \mathbb{R}^m \quad y \in \mathbb{R}^m$$

We look for coefficients  $x_1, x_2, \dots, x_n$  s.d.

$$v_1 x_1 + v_2 x_2 + \dots + v_n x_n = y \quad \Leftrightarrow \quad Ax = y$$

$$\begin{bmatrix} \square \\ \square \\ \square \end{bmatrix} \begin{bmatrix} \square \\ \square \end{bmatrix} = \begin{bmatrix} \square \\ \square \\ \square \end{bmatrix}$$

$$m \times n \quad n \times 1 \quad m \times 1$$

Food 1:

10 fats  
20 proteins  
30 sugars

Food 2:

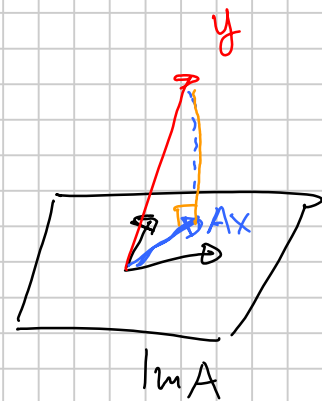
20 fats  
10 prot  
0 sugars

Mixtur has  
50 fats  
40 protein  
60 sugars

$$\begin{bmatrix} 4 \\ 3 \\ 0 \end{bmatrix} x_1 + \begin{bmatrix} 5 \\ 2 \\ 0 \end{bmatrix} x_2 = \begin{bmatrix} 6 \\ 6 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 2 \\ -3 \end{bmatrix} x_1 + \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} x_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

sum of entries = 0  $\neq$  sum of entries  $\neq 0$



When the problem is not solvable, it makes sense to ask:  
What is the closest I can get to  $y$ ?

$$\min_{x \in \mathbb{R}^n} \|Ax - y\|_2 = \min_{x \in \mathbb{R}^n} \sqrt{\sum_{i=1}^m (Ax - y)_i^2}$$

Division operators in Matlab:

$$5 / 2 \rightarrow \frac{5}{2}$$

$$5 \setminus 2 \rightarrow \frac{2}{5}$$

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \quad b = \begin{bmatrix} 5 \\ 6 \end{bmatrix} \quad Ax = b \Leftrightarrow x = A^{-1}b$$

$A \setminus b$  ⚠ NOT  $bA^{-1}$   
↳ super for  $A^{-1}b$

$X \setminus Y \rightarrow$  super for  $X \cdot Y^{-1}$

$b/A$  doesn't make sense  $b^T / A$   
 $n \times 1$     $n \times n$

Also to solve least squares problems:  $A \setminus y$

Applications: Machine Learning:

$$\min \|Xw - y\| \quad X, y \text{ data} \quad w \text{ weights (unknown)}$$

Nba salary estimation:

$$\text{salary} \approx \text{rebounds} \cdot w_1 + \text{fouls} \cdot w_2 + \text{points} \cdot w_3$$

Best estimate:

$$\min_{w \in \mathbb{R}^3} \sum_{i \in \text{Players}} (\text{salary}_i - \text{rebounds}_i w_1 - \text{fouls}_i w_2 - \text{points}_i w_3)^2$$

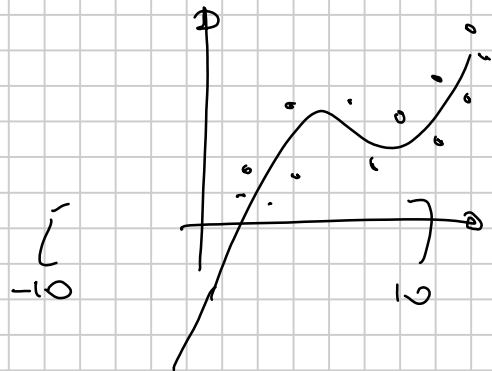
$$X = \begin{bmatrix} reb_1 & faults_1 & pts_1 \\ \vdots & \vdots & \vdots \\ reb_m & faults_m & pts_m \end{bmatrix}$$

$$y = \begin{bmatrix} salary_1 \\ \vdots \\ salary_m \end{bmatrix}$$

$$W = \begin{bmatrix} w_1 \\ w_2 \\ w_3 \end{bmatrix} \quad \min_{W \in \mathbb{R}^3} \|XW - y\|^2$$

Application: polynomial fitting

$$y \approx ax^3 + bx^2 + cx + d$$



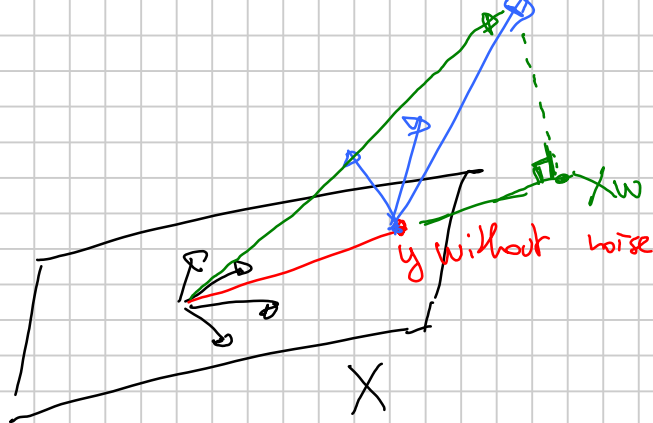
Given  $y_1, \dots, y_{1000}, x_1, \dots, x_{1000}$ , find

$$\min \sum_{i=1}^{1000} (y_i - (ax_i^3 + bx_i^2 + cx_i + d))^2 =$$

Unknowns:  $\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$

$$\min_{\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \in \mathbb{R}^4} \left\| \begin{bmatrix} x_1^3 & x_1^2 & x_1 & 1 \\ x_2^3 & x_2^2 & x_2 & 1 \\ \vdots & \vdots & \vdots & \vdots \\ x_m^3 & x_m^2 & x_m & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} - \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix} \right\|^2$$

bias column



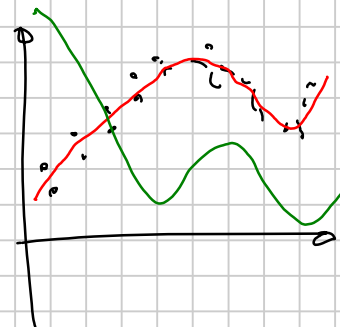
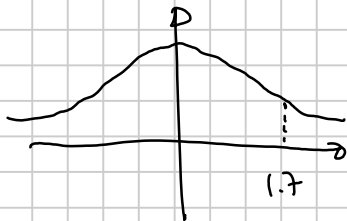
error  $\sim$  Gaussian

Maximum likelihood estimator:

If one assumes  $y_i = ax_i^3 + bx_i^2 + cx_i + d + e_i$

max. likelihood with Gaussian errors:

$$\Leftrightarrow \min \|Xw - y\|^2$$



Solvability of least squares problems

$$\left\| \begin{pmatrix} 2 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} x - \begin{pmatrix} 4 \\ 4 \\ 1 \\ 2 \end{pmatrix} \right\|^2$$

In some cases, more than one solution!

We cannot reach  $\begin{pmatrix} 4 \\ 4 \\ 1 \\ 2 \end{pmatrix}$ , but we can reach  $Ax = \begin{pmatrix} 4 \\ 4 \\ 0 \\ 0 \end{pmatrix}$

$$x = \begin{pmatrix} 2 \\ 4 \\ 0 \end{pmatrix} \text{ or } x = \begin{pmatrix} 0 \\ 0 \\ 4 \end{pmatrix} \text{ or } x = \begin{pmatrix} 1 \\ 2 \\ 2 \end{pmatrix} \dots$$

This happens because there is a vector  $z \neq 0$  such that  $Az = 0$   $z \in \text{Ker } A$

$$z = \begin{pmatrix} 2 \\ 4 \\ -4 \end{pmatrix} \text{ is such that } Az = 0$$

Non-uniqueness: if  $x$  is a solution, so is  $x+z$   $x+2z$   
 $x-37.4z$

$$A(x+2z) = Ax + \cancel{A2z}$$

Def: we say that  $A$  has full column rank

if  $\text{rk } A = \text{number of columns}$  or equivalently its columns are linear independent or equivalently  $\text{Ker } A = \{z: Az = 0\} = \{0\}$ .

Result:  $A$  has full column rank if and only if  $A^T A$  is positive definite.

Proof:  $A$  has full column rank  $\Leftrightarrow Az \neq 0$  for all  $z \neq 0$

$$\Leftrightarrow \|Az\| \neq 0 \text{ for all } z \neq 0 \Leftrightarrow \|Az\|^2 \neq 0 \text{ for all } z \neq 0$$

$$\Leftrightarrow (Az)^T (Az) = z^T A^T A z \neq 0 \text{ for all } z \neq 0 \Leftrightarrow A^T A \text{ is pos. def.}$$

Note that

$$\min_{x \in \mathbb{R}^n} \frac{1}{2} \|Ax - y\|^2 = \min \frac{1}{2} (Ax - y)^T (Ax - y)$$

$$= \min \frac{1}{2} (Ax)^T Ax - \underbrace{\frac{1}{2} (Ax)^T y}_{\text{equal}} - \underbrace{\frac{1}{2} y^T (Ax)}_{\text{equal}} + \frac{1}{2} y^T y$$

$$= \min_{x \in \mathbb{R}^n} \underbrace{\frac{1}{2} x^T A^T A x}_Q - \underbrace{x^T A^T y}_{q^T} + \underbrace{\frac{1}{2} y^T y}_{\text{constant}}$$

gradient:  $A^T A x - A^T y$

Hessian:  $A^T A$

For a quadratic function, the minimum is unique if and only if  $Q = A^T A > 0$  is pos. definite  $\Leftrightarrow A$  has full column rank

minimum:  $x = -Q^{-1} q = (A^T A)^{-1} (A^T y)$   $\rightarrow$   
 closed-form expression for the solution!

Solution algorithm:

Input:  $A \in \mathbb{R}^{m \times n}$  full col. rank,  $y \in \mathbb{R}^m$

Output:  $x \in \mathbb{R}^n$  that solves  $x = \arg \min \|Ax - y\|$

1. Compute  $A^T A$   $n \times n$   $m \times n \rightarrow n \times n$   $\sim \cancel{2} mn^2$

2. Compute  $A^T y$   $n \times m$   $m \times 1 \rightarrow n \times 1$   $\sim 2mn$

3. Solve the lin. system  $(A^T A)x = A^T y$   $\sim \cancel{2} \frac{1}{3} n^3$   
 square  $x = (A^T A)^{-1} (A^T y)$

Linear in the larger dimension, quadratic in the smaller

Trick:  $A^T A$  is symmetric:  $2mn^2$  becomes  $mn^2$

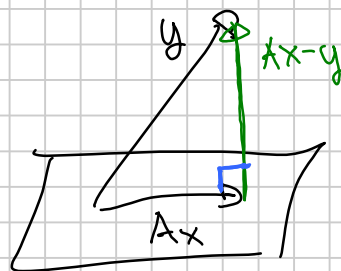
Trick: the linear system has a symmetric pos. definite matrix

We can use a better algorithm than Gaussian elimination / LU factorization: Cholesky factorization

$\frac{2}{3}n^3$  becomes  $\frac{1}{3}n^3$ .

This algorithm is known as method of normal equations

$$A^T A x = A^T y \Leftrightarrow A^T (Ax - y) = 0$$



The residual  $Ax - y$  is perpendicular to the plane spanned by the columns of  $A$ .

Consequence: the solution of  $\min \|Ax - y\|$  is given

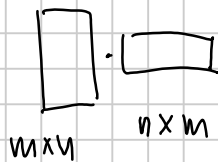
by  $x = (A^T A)^{-1} A^T y$



Def:  $(A^T A)^{-1} A^T =: A^+$  is called the pseudoinverse of  $A \in \mathbb{R}^{m \times n}$ ,  $m > n$  with full column rank.

Note that  $A^+ A = (A^T A)^{-1} (A^T A) = I$

but  $AA^+ \neq I$



is an  $m \times m$  matrix with rank  $n < m$  and so cannot be the identity.

If  $A$  square  $(A^T A)^{-1} = A^{-1} (A^T)^{-1}$

$$\Rightarrow A^+ = (A^T A)^{-1} A^T = A^{-1} \cancel{(A^T)^{-1}} A^T = A^{-1}$$