Least squares problems and QR factorization

We see a different algorithm to solve least-squares problems using the QR factorization of A.

Start from

$$A = QR, \quad Q = \begin{bmatrix} Q_0 & Q_c \end{bmatrix}, \quad R = \begin{bmatrix} R_0 \\ 0 \end{bmatrix}.$$

Since orthogonal matrices preserve the 2-norm,

$$\begin{aligned} \|A\mathbf{x} - \mathbf{y}\| &= \|Q^T (A\mathbf{x} - \mathbf{y})\| = \|Q^T QR\mathbf{x} - Q^T \mathbf{y}\| \\ &= \|R\mathbf{x} - Q^T \mathbf{y}\| = \left\| \begin{bmatrix} R_0 \\ 0 \end{bmatrix} \mathbf{x} - \begin{bmatrix} Q_0^T \\ Q_c^T \end{bmatrix} \mathbf{y} \right\| \\ &= \left\| \begin{bmatrix} R_0 \mathbf{x} - Q_0^T \mathbf{y} \\ Q_c^T \mathbf{y} \end{bmatrix} \right\|. \end{aligned}$$

Solving least squares with QR

$$\|A\mathbf{x} - \mathbf{y}\| = \left\| \begin{bmatrix} R_0 \mathbf{x} - Q_0^T \mathbf{y} \\ Q_c^T \mathbf{y} \end{bmatrix} \right\|$$

How can we minimize the norm of this vector?

Bottom block same value, regardless of \mathbf{x} . The squares of those entries will always be in the sum.

Top block We can choose **x** to make its entries smaller. Can we get $R_0 \mathbf{x} - Q_0^T \mathbf{y} = 0$? Yes, if R_0 invertible.

When is R_0 invertible?

Related to a result we have seen earlier. If A = QR, with Q orthogonal, then

$$A^{T}A = (QR)^{T}(QR) = R^{T} \underbrace{Q^{T}Q}_{=I} R = R^{T}R = \begin{bmatrix} R_{0}^{T} & 0 \end{bmatrix} \begin{bmatrix} R_{0} \\ 0 \end{bmatrix} = R_{0}^{T}R_{0}.$$

A has full column rank $\iff A^T A$ is posdef $\iff A^T A = R_0^T R_0$ is invertible $\iff R_0$ is inverbile.

(Note for your future self revising: $R_0^T R_0$ is the Cholesky factorization of $A^T A$, which we shall see later in the course.)

Algorithm

We have proved the following.

Lemma

If
$$A = QR = \begin{bmatrix} Q_0 & Q_c \end{bmatrix} \begin{bmatrix} R_0 \\ 0 \end{bmatrix}$$
 (and has full column rank), then the solution of min $\|A\mathbf{x} - \mathbf{y}\|$ is given by $\mathbf{x} = R_0^{-1}(Q_0^T)\mathbf{y}$.

The thin QR factorization $A = Q_0 R_0$ contains all we need here. Corollary formula for the pseudoinverse $A^+ = R_0^{-1} Q_0^T$. Cost:

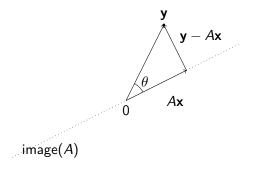
- 1. Thin QR: $O(mn^2)$
- 2. Multiplication $\mathbf{c} = (Q_0^T)\mathbf{b}$: O(mn).
- 3. Triangular system solution $R_0 \mathbf{x} = \mathbf{c}$: $O(n^2)$ with back-substitution.

The dominant part is the thin QR computation.

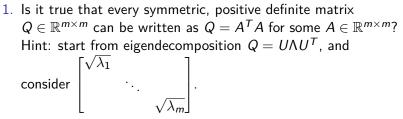
The geometric picture

- **y** is split into two orthogonal components: A**x** and **y** A**x**.
 - $A\mathbf{x} = Q_0 R_1 R_0^{-1} Q_0^T \mathbf{y} = Q_0 Q_0^T \mathbf{y}$ gives the projection of \mathbf{y} onto Im A. It has length $||Q_0^T \mathbf{y}||$.

► The residual $||A\mathbf{x} - \mathbf{y}||$ (i.e., the optimum value) is $||Q_c^T \mathbf{y}||$. The vectors \mathbf{y} , $A\mathbf{x}$ and $A\mathbf{x} - \mathbf{y}$ form a right triangle with side lengths $||\mathbf{y}||$, $||Q_0^T \mathbf{y}||$, $||Q_c^T \mathbf{y}||$.



Exercises



Book references: Demmel, 3.2.2; Trefethen-Bau, Lecture 11.