

Least squares problems and QR factorization

Alternative way to solve linear least-squares problems: start from

ortho of Γ tri

$$\underline{A = QR}, \quad Q = \begin{matrix} m & n & m-n \\ Q_1 & \vdots & Q_2 \end{matrix}, \quad R = \begin{matrix} n & & \\ R_1 & & \\ \vdots & & \\ 0 & & \end{matrix} \cdot \begin{matrix} \begin{matrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{matrix} \\ \vdots \\ 0 \end{matrix}$$

$A = QR = Q_1 \cdot R_1 + Q_2 \cdot 0 = Q_1 R_1$

$m-n$

Trick: since orthogonal matrices preserve norm-2,

$$\begin{aligned} \|Ax - b\| &= \|Q^T(Ax - b)\| = \|Q^T QRx - Q^T b\| \\ &= \|Rx - Q^T b\| = \left\| \begin{bmatrix} R_1 \\ 0 \end{bmatrix} x - \begin{bmatrix} Q_1^T \\ Q_2^T \end{bmatrix} b \right\| \\ &= \left\| \begin{bmatrix} R_1 x - Q_1^T b \\ Q_2^T b \end{bmatrix} \right\|. \end{aligned}$$

For every vector $\underline{x} \in \mathbb{R}^n$

$$A = QR$$

$$\begin{aligned} \|\underline{Ax} - \underline{b}\| &= \|\underline{Q}^T(\underline{Ax} - \underline{b})\| = \|\underbrace{\underline{Q}^T \underline{Q}}_{\underline{I}} \underline{R} \underline{x} - \underline{Q}^T \underline{b}\| = \\ &= \|\underline{R} \underline{x} - \underline{Q}^T \underline{b}\| = \left\| \begin{bmatrix} R_1 \\ 0 \end{bmatrix} \underline{x} - \begin{bmatrix} Q_1^T \\ Q_2^T \end{bmatrix} \underline{b} \right\| = \end{aligned}$$

$$\begin{aligned} &= \left\| \begin{bmatrix} R_1 \underline{x} \\ 0 \end{bmatrix} - \begin{bmatrix} Q_1^T \underline{b} \\ Q_2^T \underline{b} \end{bmatrix} \right\| = \left\| \begin{bmatrix} R_1 \underline{x} - Q_1^T \underline{b} \\ -Q_2^T \underline{b} \end{bmatrix} \right\| \end{aligned}$$

$\underbrace{\hspace{10em}}_{\text{depends on } x}$
 $\underbrace{\hspace{10em}}_{\text{does not depend on } x}$

$$\left\| \begin{bmatrix} R_1 \underline{x} - Q_1^T \underline{b} \\ -Q_2^T \underline{b} \end{bmatrix} \right\| \geq \|Q_2^T \underline{b}\|$$

$$\left\| \begin{bmatrix} c(x) \\ d \end{bmatrix} \right\| = \sqrt{c_1^2 + c_2^2 + \dots + c_n^2 + d_1^2 + \dots + d_{m-n}^2}$$

$\uparrow \quad \uparrow \quad \uparrow$

$$\geq \sqrt{d_1^2 + \dots + d_{m-n}^2}$$

If I choose x s.t. $R_1 x = Q_1^T b$

then the first block $R_1 x - Q_1^T b$ becomes 0

\Rightarrow the value of x such that $R_1 x = Q_1^T b$ is the solution of the LS problem

$$x = R_1^{-1} Q_1^T b$$

$n \times n$

Solving least squares with QR

$$\|Ax - b\| = \left\| \begin{bmatrix} R_1 x - Q_1^T b \\ Q_2^T b \end{bmatrix} \right\|$$

How can we minimize the norm of this vector?

Bottom block: same value, regardless of x . The squares of those entries will always be in the sum.

Top block I can choose x to make its entries smaller. Can I get $R_1 x - Q_1^T b = 0$? **Yes**, if R_1 invertible.

When is R_1 invertible?

Related to a result we have seen earlier. If $A = QR$, with Q orthogonal, then

$$A^T A = (QR)^T (QR) = R^T \underbrace{Q^T Q}_{=I} R = R^T R = \begin{bmatrix} R_1^T & 0 \end{bmatrix} \begin{bmatrix} R_1 \\ 0 \end{bmatrix} = R_1^T R_1.$$

A has full column rank $\iff A^T A$ is posdef $\iff A^T A = R_1^T R_1$
is invertible $\iff R_1$ is invertible.

(Note for the future: $R_1^T R_1$ is the Cholesky factorization of $A^T A$.)

Is R_1 invertible? $A = QR = Q_1 R_1$

$$\begin{aligned} \underline{A^T A} &= (R_1^T Q^T)(QR) = R_1^T \underbrace{(Q^T Q)}_I R = R_1^T R = \\ &= \begin{bmatrix} R_1^T & 0 \end{bmatrix} \cdot \begin{bmatrix} R_1 \\ 0 \end{bmatrix} = R_1^T R_1 + 0 \cdot 0 = \underline{R_1^T R_1} \end{aligned}$$

A has full col. rank $\Leftrightarrow A^T A$ is pos. def

$\Leftrightarrow A^T A$ is invertible $\Leftrightarrow R_1^T R_1$ is invertible

\uparrow $\Leftrightarrow R_1$ is invertible
(*)

$A^T A$ is posdef if it has no 0 eigenvalue

(*) If R_1 invertible, then $(R_1^T R_1)^{-1} = R_1^{-1} (R_1^T)^{-1}$
 $\Rightarrow R_1^T R_1$ is invertible

If R_1 is singular, then $R_1^T R_1$ is not invertible

$\det(R_1^T R_1) = \det(R_1^T) \det R_1$
 if this is zero...
 then this is zero as well



Rank: Steps in red make sense only because R_1 is square

Recap

If $A = QR = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} R_1 \\ 0 \end{bmatrix}$ (and has full column rank), then the solution of $\min \|Ax - b\|$ is given by $x = R_1^{-1}(Q_1^T)b$.

Note that 'thin QR' $A = Q_1R_1$ contains all we need here.

This gives (of course) the same solution x as the normal equations method. Indeed, some algebra gives

$$(A^T A)x = A^T b$$

$$A^T A = R_1^T R_1, \quad A^T b = R_1 Q_1^T b.$$

so the two methods solve similar linear systems:

Normal equations	QR-based method
$R_1^T R_1 x = R_1^T Q_1^T b$	$R_1 x = Q_1^T b.$

Exercises

1. Is it true that every symmetric, positive definite matrix $M \in \mathbb{R}^{m \times m}$ can be written as $B^T B$ for some $B \in \mathbb{R}^{m \times m}$?
Hint: start from eigendecomposition $M = Q \Lambda Q^T$, and

consider
$$\begin{bmatrix} \sqrt{\lambda_1} & & \\ & \ddots & \\ & & \sqrt{\lambda_m} \end{bmatrix}.$$