

Intro to Learning in SD -2

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2- Neural Networks for Graphs

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DRAFT, please do not circulate!

www.di.unipi.it/groups/ciml



Dipartimento di Informatica
Università di Pisa



**Computational Intelligence &
Machine Learning Group**

Learning in Structured Domain

Plan in 2 lectures

1. Recurrent and Recursive Neural Networks

Extensions of models for supervised and unsupervised learning in structured domains

- Extensions of models for learning in structured domains
- Motivation and examples (structured data)
- The structured data (recursive)
- Recursive models: RNN and RecNN
- Recursive Cascade Correlation & other recursive approaches

2. Moving to DPAG and Graphs: the role of causality

- Recap SD1
- Causality for Recurrent and Recursive models &
- Contextual approaches (CRCC and DPAGs)
- Neural Networks for graphs

By a journey through the causality assumption!

Recup SD-1:

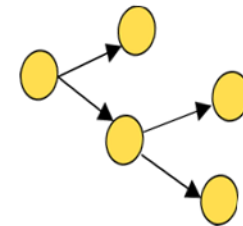
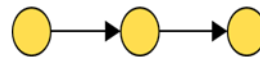
Adaptive processing of SD

- The problem: there has been no systematic way to extract features or metrics relations between examples for SD
- **Goal:** to learn a mapping between a structured information domain (SD) and a discrete or continuous space (*transduction*).
- **Recursive** and parametric realization of the transduction function
- *Adaptive* by Neural Networks: RecNN
 - Pro: RecNN adapts the model to the hierarchal data
 - Cons: Causality issue (*): it affects the computational power of RecNN and the class of graphs ! → new models!

The scenario, terms (and trends)

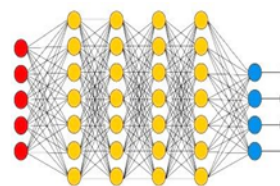
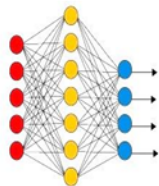
Input Domain		
Flat (vectors) (e.g. F.F.NN)	Sequences (RNN)	Structures (trees/graphs)

● vector label [...]



Representation of the input at multiple-levels of abstraction

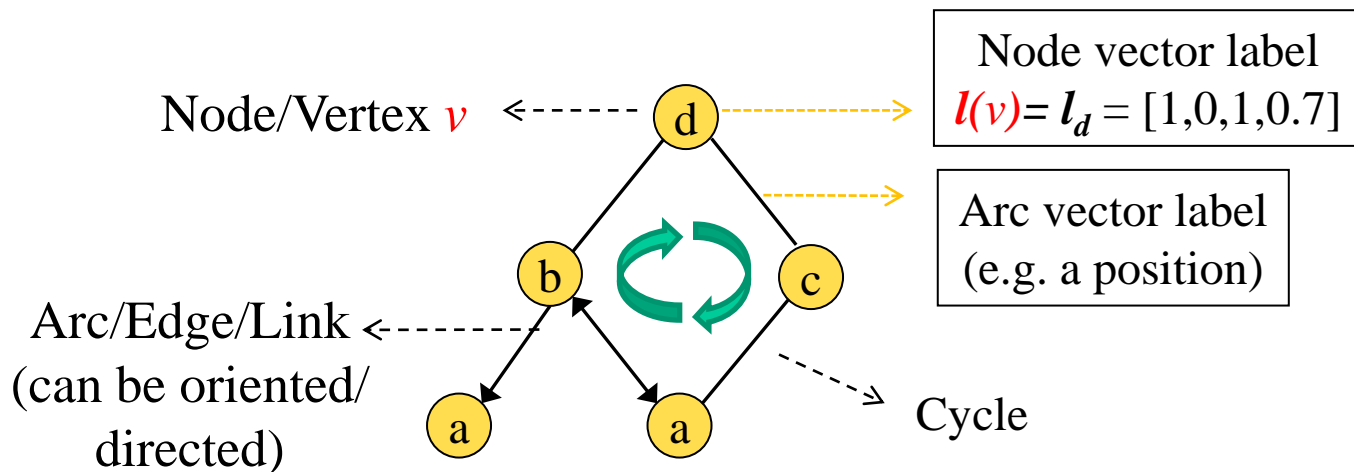
Layering	
Shallow	Deep



“Deep and wide” approaches

Our graphs (in the following)

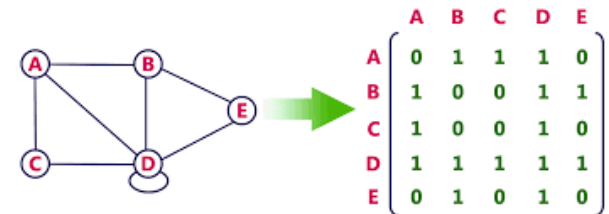
Labeled graphs g



Graph Representations

The problem: there has been no systematic way (of general validity for any task) to extract features or metrics relations between examples for SD

- **Features based** representations are incomplete (or strongly task-dependent, e.g. topological indexes)
- **Adjacent/incident matrix** representations (or other fixed-sizes representations). Issues:
 - Over-dim./incomplete (wasteful by padding/lose inf.)
 - Alignment among different graphs
 - Topological order (make difficult the generalization)
- ML issues for the high proportion between combinatorial number of possible data examples and available data
- “The ability to treat the proper **inherent nature of the input data** is the key feature for a successful application of the machine learning methodologies.”



Learning Models for SD - Memento



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Our “mantra”:

Instead of moving *data to models*
(e.g. Graphs into vectors or trees into sequences, with
alignment problems, loose of information, etc.)
we move *models to data*

Learning in Structured Domain

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- Recursive models: RNN and RecNN
- Recursive Cascade Correlation & other recursive approaches

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- Contextual approaches (CRCC and DPAGs)
- Neural Networks for graphs

*By a journey through the causality assumption! **

CRCC: introduction

- Analysis of the **causality** assumption for Recurrent and Recursive neural computing models
- Partial relaxation (or **extension**) of the causality assumption
- First approach to deal with *contextual information* in SD by Recursive models

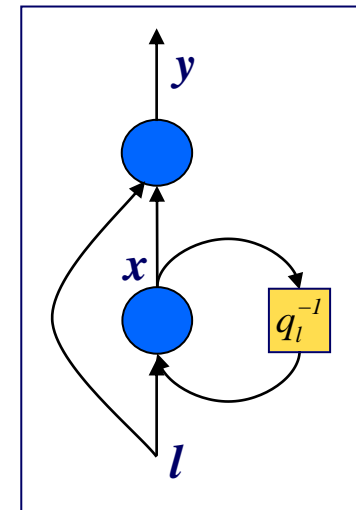
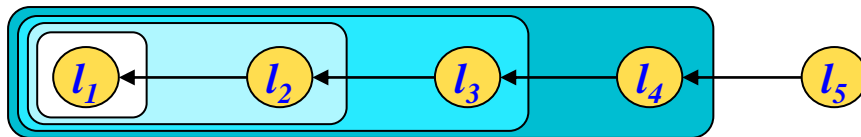
Causal Systems

- Recurrent NN models are based on the **Causality** assumption, i.e. RNN are only able to memorize past information

A system is causal if the output at time t_0 only depends on inputs at time $t \leq t_0$

necessary and
sufficient for
internal state

$$\begin{cases} \mathbf{x}(t) = \tau(\mathbf{x}(t-1), \mathbf{l}(t)) \\ \mathbf{y}(t) = g(\mathbf{x}(t), \mathbf{l}(t)) \end{cases}$$



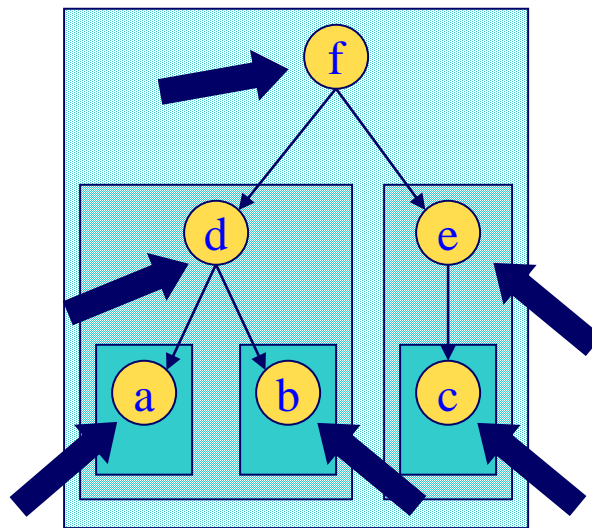
Graphical
model

Shift operator
 q^{-1}

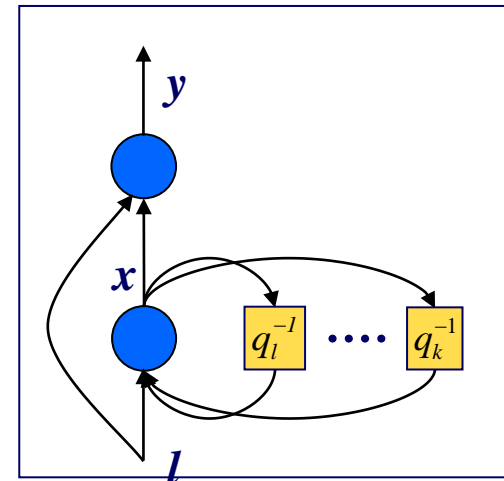
Causal Systems in Structured Domain (RecNN)

- The causality concept can be generalized to structured data transductions as follows

A system is causal if its output for a node v only depends on v and its descendants



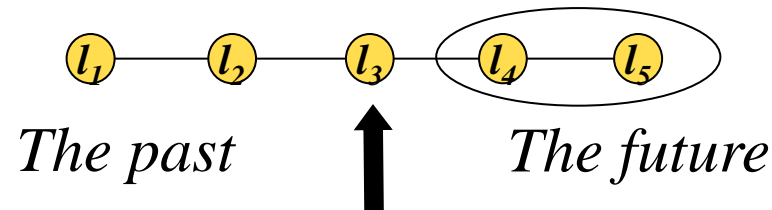
Unfolding the encoding
process through structure



$$\begin{cases} x(v) = \tau(x(\text{ch}[v]), l(v)) \\ y(v) = g(x(v), l(v)) \end{cases}$$

Drawbacks of Causal Systems for sequence domain

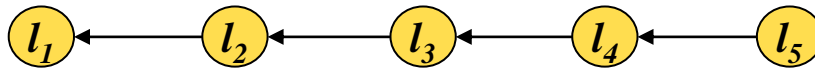
- Several prediction tasks involving **sequences** require past and “future” information (*on known sequences*)
 - DNA and Protein analysis / Language understanding / ...



Causality hampers to consider the right part

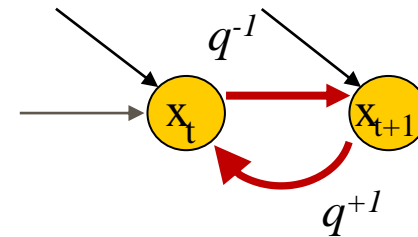
- Contextual information for **structured** domains: whenever the meaning of a sub-structure depends on the context in which it is found
 - some classes of transductions **cannot** be computed by causal models (also some causal transduction !!!)
 - extension of the class of graphs
 - *Properties in flat domains cannot be trivially “exported” in SD!*

Premise: Overcome Causality for Sequences



$$\begin{cases} \mathbf{x}(t) = \tau(\mathbf{x}(t-l), \mathbf{x}(t+l), l(t)) \\ \mathbf{y}(t) = g(\mathbf{x}(t), l(t)) \end{cases}$$

Unfolding **with cycles**



- A possible **bi-causal** model: however, this is not easily implementable
 - **Cycles**: State equations and enc. net. (unfolding) become dynamical systems due to mutual dependencies
 - Different solutions are available (e.g. *bidirectional* approaches for RNN using a different state for left-to-right or right-to-left encoding). See CNS course
 - *It is not easy to extend them to structures* (many possible paths, *not just* left-to-right or right-to-left)

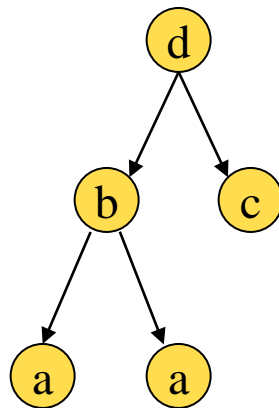
Overcome the Causality Assumption for SD: CRCC



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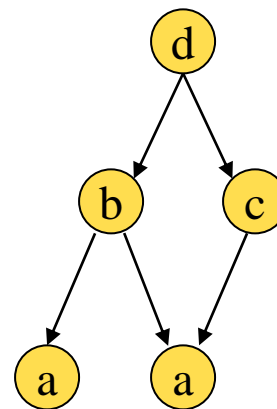
The Structure Domain

- Context processing relevance
- CRCC: Cascade **Recursive** Cascade Correlation:
- Effects over sequences and trees
- Moving to trees and DPAGs
- Examples of Results



Rooted Tree

Supersource

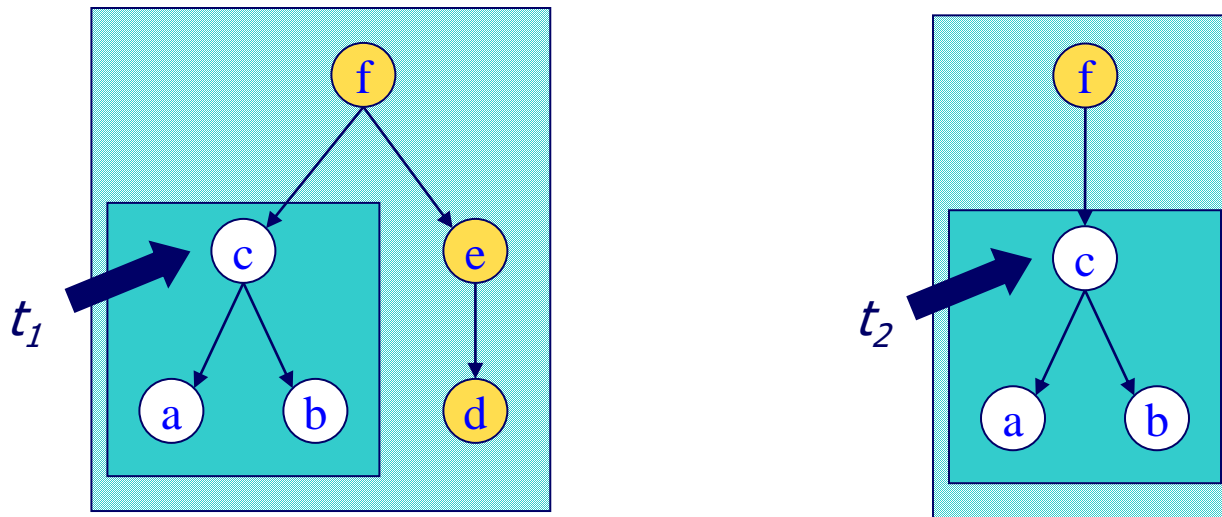


DPAG

Contextual Target Functions

Relevance of contextual processing (I)

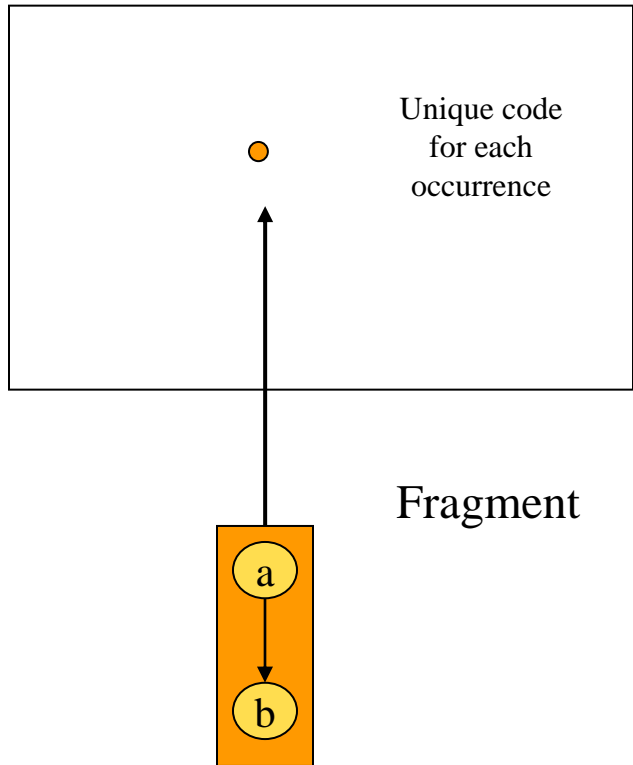
contextual IO-isomorphic transductions
(where causal models fail)



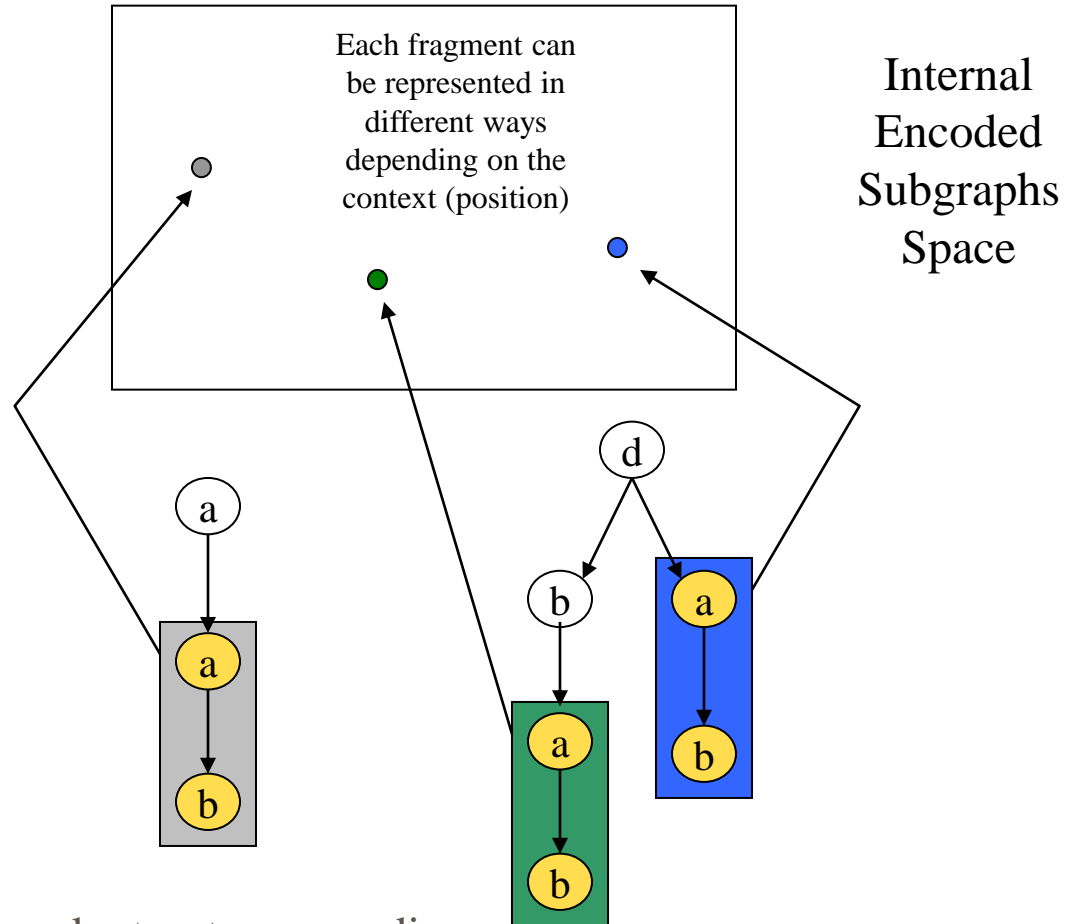
$$\begin{aligned} \text{Target}(t_1) &\neq \text{Target}(t_2) \\ \text{out}_{\text{RecNN}}(t_1) &= \text{out}_{\text{RecNN}}(t_2) \\ \mathbf{C}(x_k(c_1)) &\neq \mathbf{C}(x_k(c_2)) \end{aligned}$$

Example on the PCA Code Plot

Causal mapping



Contextual mapping

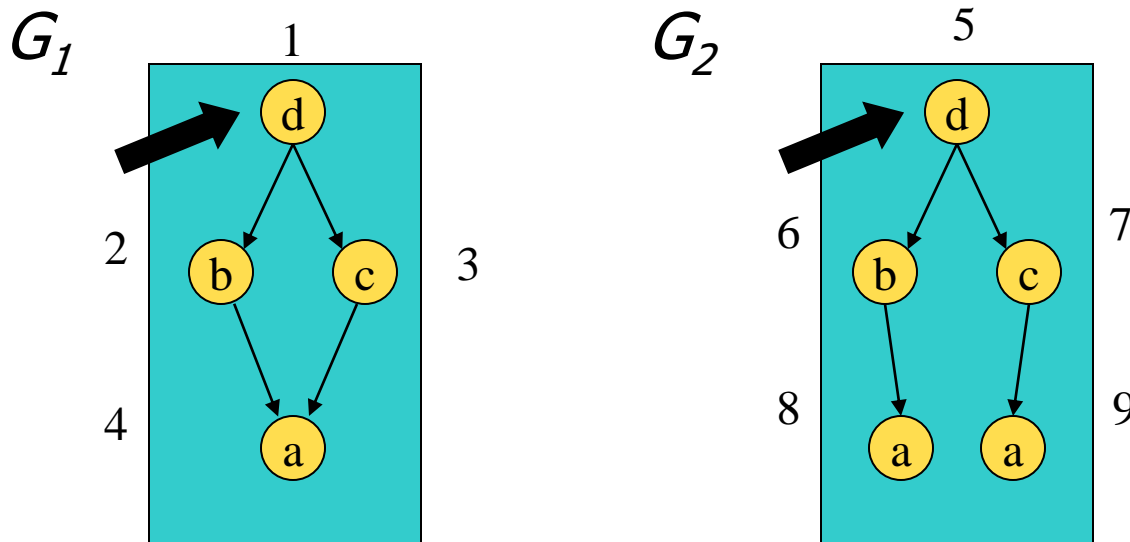


More expressive sub-structure encoding

DPAG representation: a counter-example

Relevance of contextual processing (II)

- Two different DPAG necessarily mapped into the same output by RecNN (*supersource* causal transductions) (*i.e. causal models fail*)

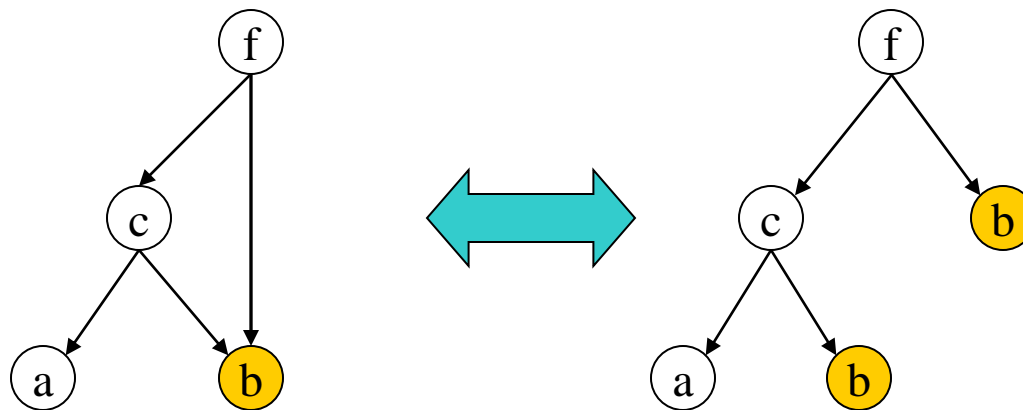


- CRCC **can** distinguish G_1/G_2 (*context for node "a" is different*)
- RecNN **cannot** (*b and c see the same state values*)

DPAGs are not trees !

Relevance of contextual processing (III)

- Causal models allow to rewrite a DPAG as an equivalent tree



- CRCC distinguish them !
- *We (really) extended the domain from trees to DPAGs !*

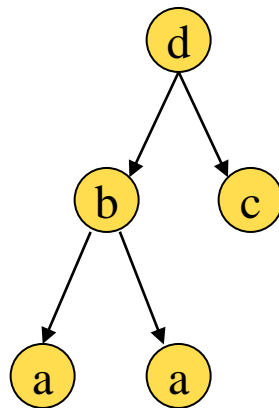
Overcome the Causality Assumption for SD: CRCC



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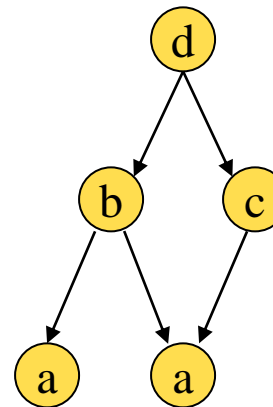
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Rooted Tree

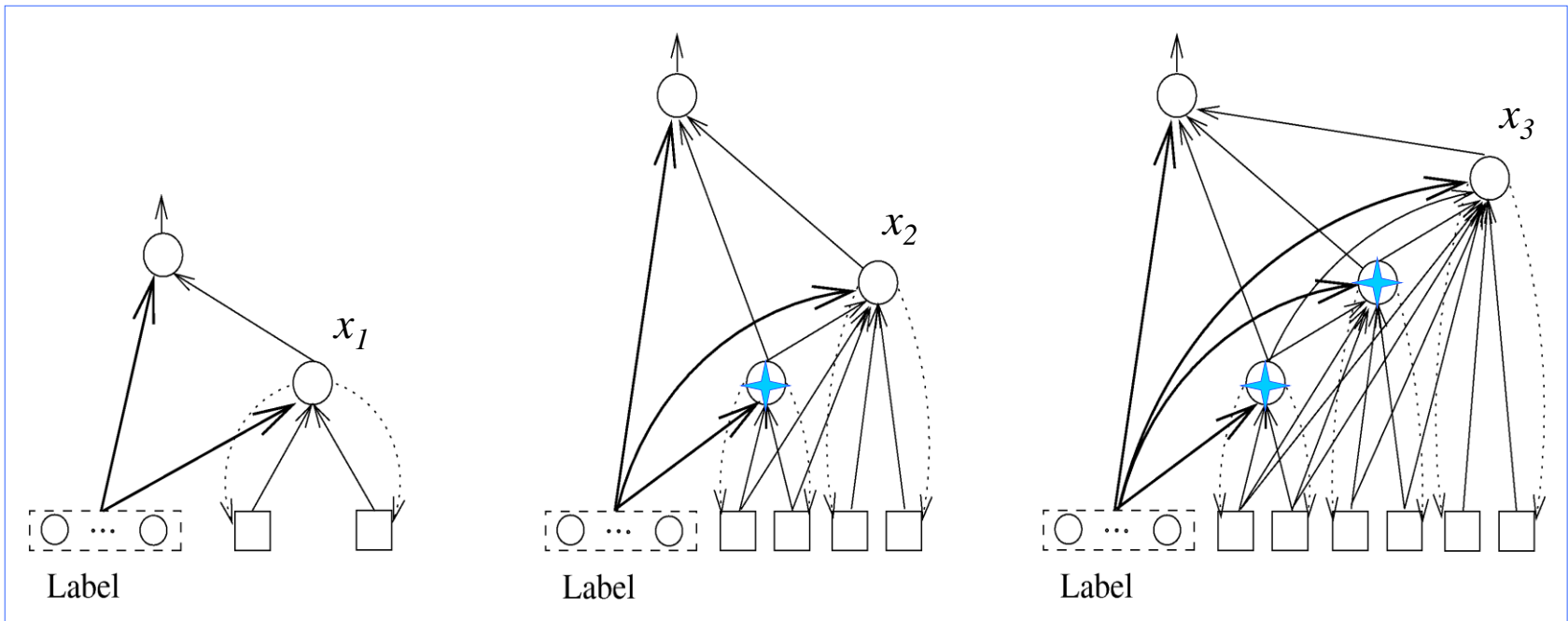
Supersource



DPAG

Premise: recall of the RCC Approach

By a Recursive Cascade Correlation we can realize the recurrent/recursive network by a **constructive approach**:
The hidden units are added to the network, and frozen, during the training



CRCC Approach

- We proposed an instance of Contextual RecCC suitable for implementation with Recursive Cascade Correlation
- Each time a unit is **frozen** ✨, the portion of its (memorized) state encodes knowledge of the **whole** input structure
- The following units can access to $\text{pa}[v]$ (parents of each v) through the q^{+1} operator without introducing cycles in the state equations and encoding networks

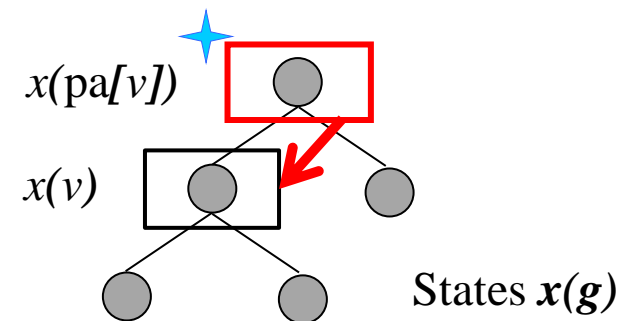
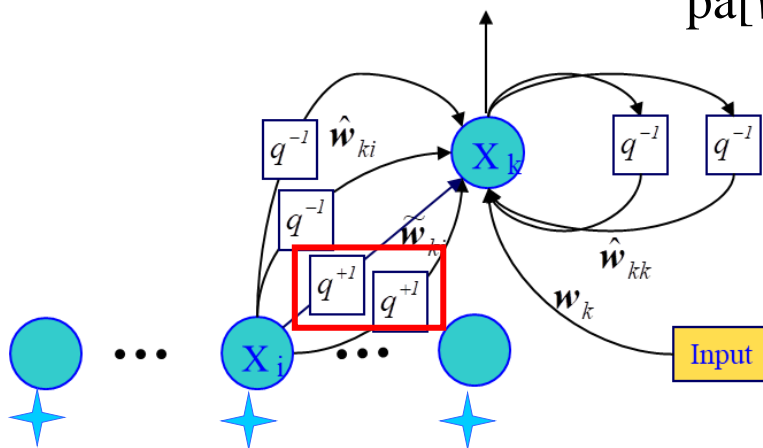
The CRCC Contextual Approach

- Each time a unit is frozen, the portion of its (memorized) state encodes knowledge of “the whole” structure

$$\begin{aligned}
 x_1(v) &= \tau_1(x_1(\text{ch}[v]), l(v)) \\
 x_2(v) &= \tau_2(x_2(\text{ch}[v]), x_1(\text{ch}[v]), x_1(\text{pa}[v]), l(v)) \\
 &\vdots \\
 &\vdots \\
 x_m(v) &= \tau_m(x_m(\text{ch}[v]), x_{m-1}(\text{ch}[v]), \boxed{x_{m-1}(\text{pa}[v])}, \dots, x_1(\text{ch}[v]), \boxed{x_1(\text{pa}[v])}, l(v))
 \end{aligned}$$

unit m frozen unit m-1 frozen unit 1

$\text{pa}[v]$: set of parents of v



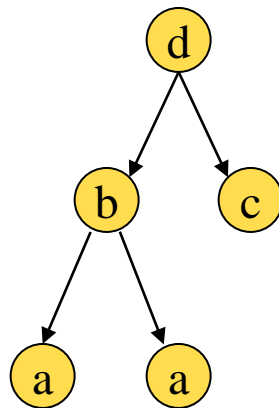
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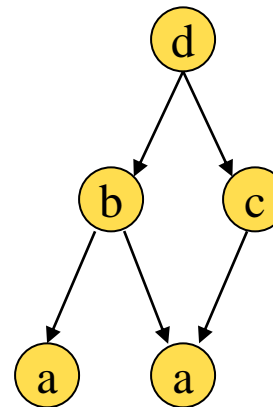
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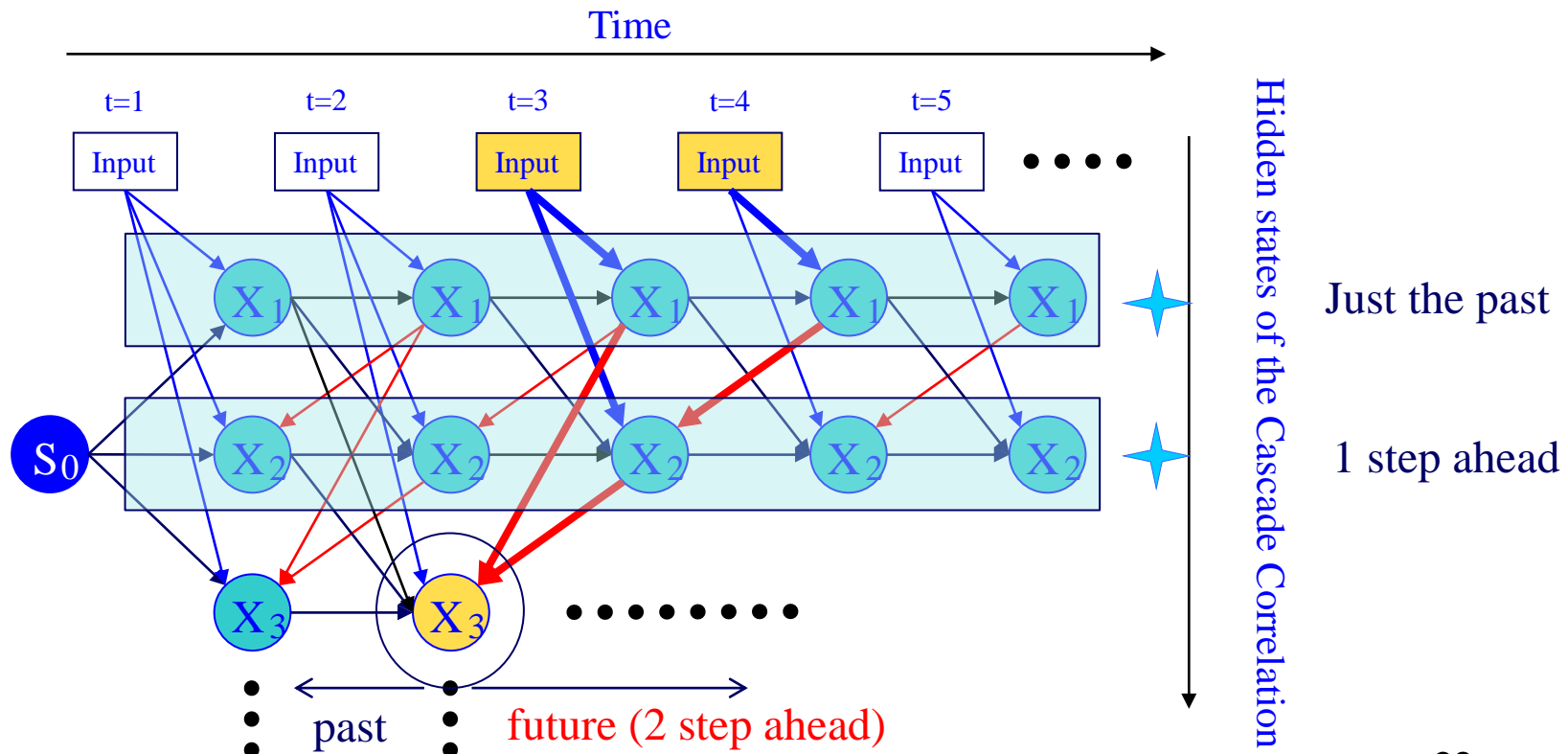
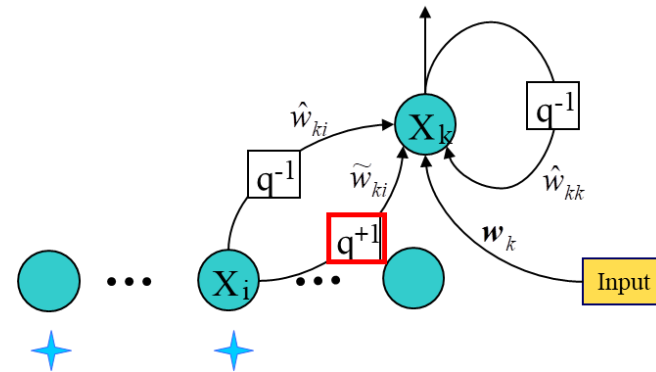
Supersource



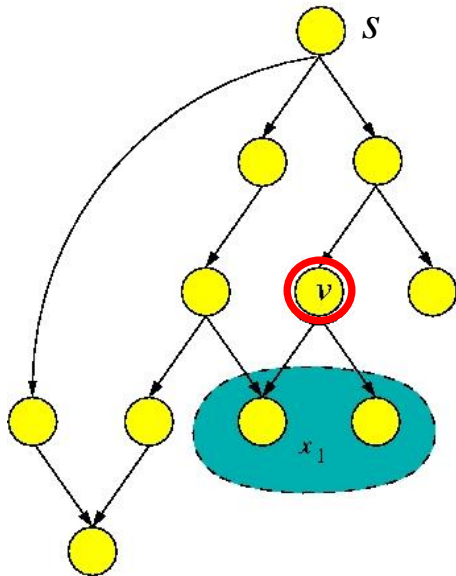
DPAG

Example: unfolding CRCC on a sequence

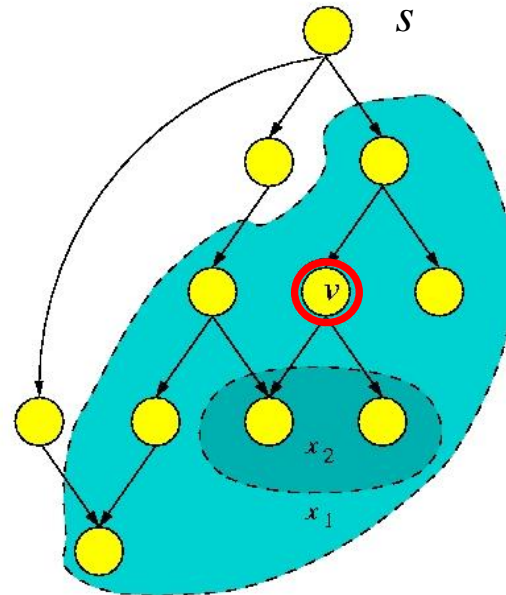
We can gain information on the "future" proportionally to the number of hidden units



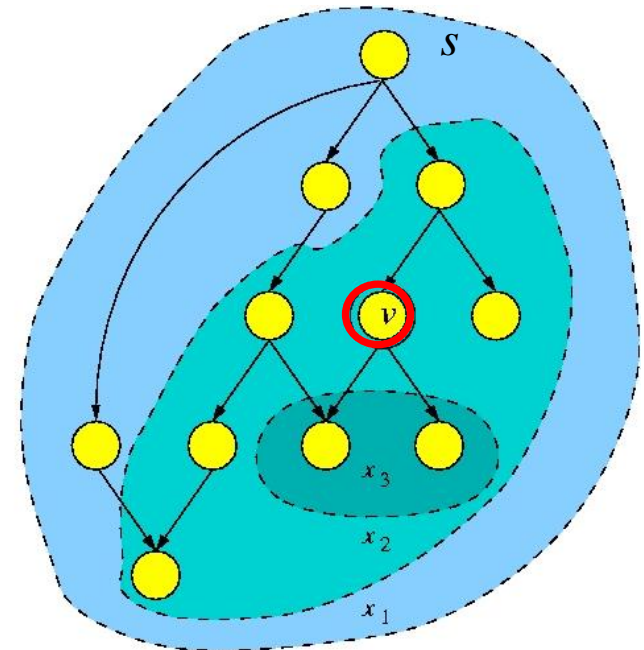
Example: $C(\bullet)$ for DPAGs



$C(x_1(v))$



$C(x_2(v))$



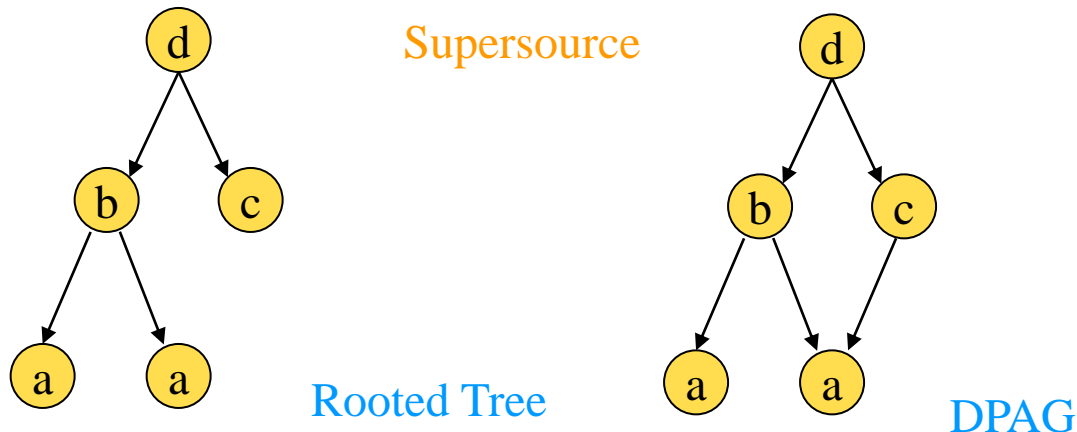
$C(x_3(v))$

The context grows (via `in_set`) including all sub-DPAG met along the
(inverse) path $v \rightarrow s$ and $\downarrow v \rightarrow s$
descendants

Overcome the Causality Assumption for SD: CRCC

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Theory



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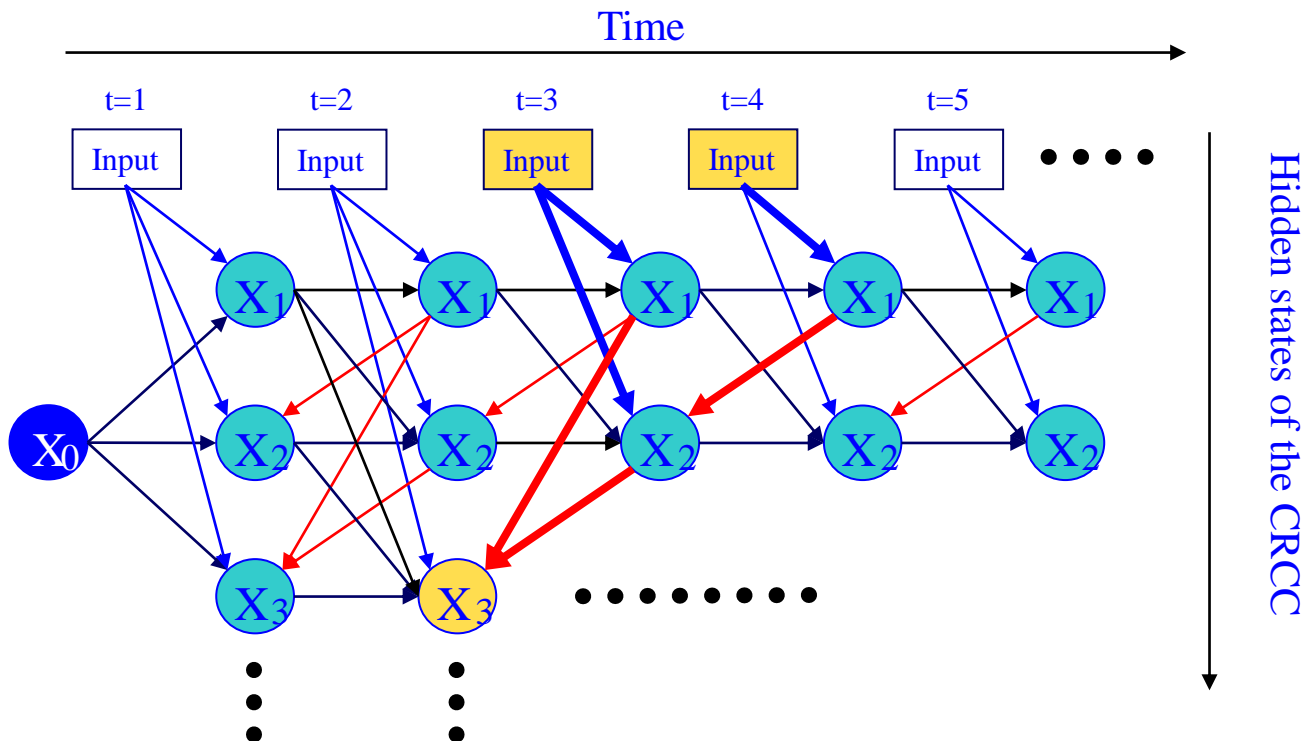
- Theoretical results have introduced to characterize the *computational power* of CRCC (class of computable functions/transductions vs causal models)
- Solving the examples before:
 - extension to *contextual* IO-isomorphic transductions,
 - e.g. $Target(v)=f(\text{whole structure})$: future dependencies.
 - extension to the class of supersource (causal) transductions involving DPAGs that cannot be computed by causal models
 - while supporting all the function computable by RCC
 - And also:
- Formal compact expression of the “context window”
- Proof of computational power of CRCC (**abstracting from neural realization**)

Example: $C(\bullet)$ for Sequences



$$C(x_k(v)) = \bigcup_{i=1}^{k-1} x_i \cdot \downarrow v_{t+k-i} \cup x_k \cdot \downarrow v_{t-1}$$

It is possible to formalize the **context** giving formal expression of state functional dependencies
Example here for sequences.



Universal Approximation



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- B. Hammer, A. Micheli, A. Sperduti. **Universal Approximation Capability of Cascade Correlation for Structures** *Neural Computation* **17**, 1109–1159 (2005)
- RecCC can approximate every measurable functions from sequences and trees to real values (in spite of their restricted recurrent architecture) for finite sets.
- **CRCC: Universal approximation capability extended to classes of labeled DPAGs**

f approximated up to any desired degree of accuracy
(up to inputs of arbitrary small probability)

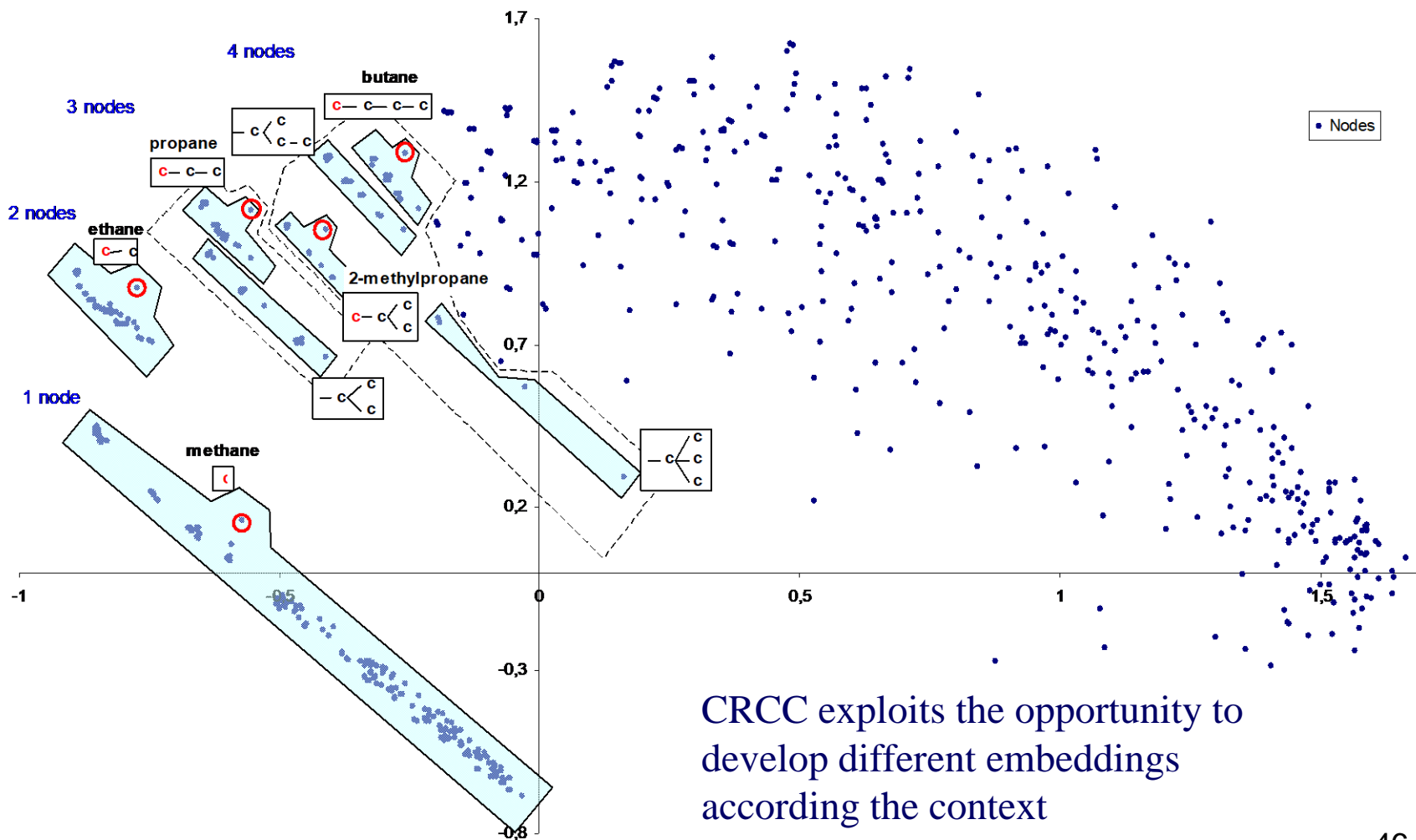
$$P(x \in DPAG : |f(x) - CRCC(x)| > \delta) < \varepsilon$$

Context in a CRCC Application



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PCA of the representation of the sub-structures developed by CRCC
for a chemical regression task



CRCC Conclusions

- Show advantages of including “context” (including parents)
 - Extension of the computation capability
 - Extension of the classes of data to DPAGs
 - Expressive encoding of substructures
 - Performance where causality assumption is unknown
- However, CRCC still requires topological order and supersource, still recursive dynamics: DPAGs/DAGs
- ... New approaches : by retaining and extending context, removing **causality**/recursion ?
 - Yes, ***Move to graphs!***

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Extensions of models for supervised and unsupervised learning in structured domains

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- The structured data (recursive)
- Recursive models: RNN and RecNN
- Recursive Cascade Correlation & other recursive approaches

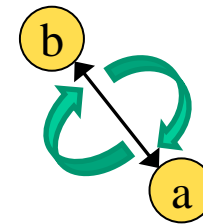
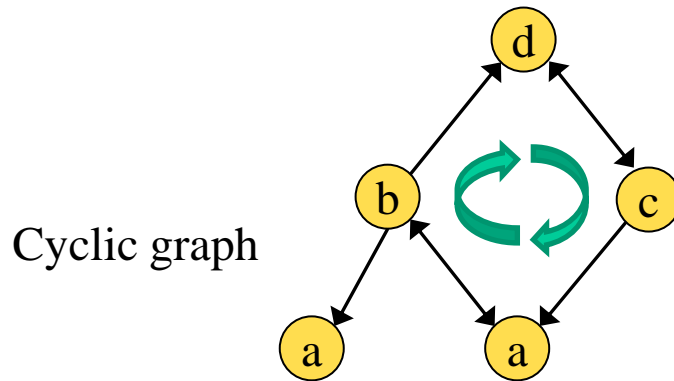
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*By a journey through the
causality assumption!*

Graphs by NN: Cycles

Causality assumption in RecNN introduce issues in processing **cycles** (due to the mutual dependencies among state values)



Occuring also for
undirected edges!

How to deal with cycles
and causality?

Main approaches for graphs by NN

Different classes of approaches:

1. Rewriting the graph:

- Atomic representation of cycles: e.g. functional groups in chemistry
- To trees/DAGs (e.g. SMILES representation in chemistry)

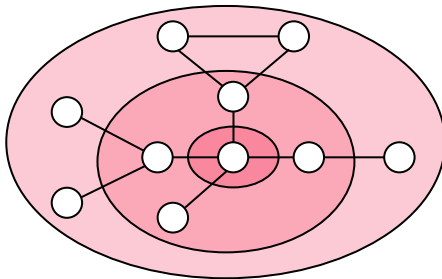
2. RecNN by explicitly treating the cyclic dynamics by contractive constraints (GNN, GraphESN) [1,2]

3. Layering: contextual non-recursive approaches (NN4G [3] /Conv. NN for graphs [4]) → Deep NN for graphs (or Conv/spatial approaches)

1. Scarselli, Gori, Tsoi, Hagenbuchner, Monfardini. IEEE TNN, 2009.
2. Gallicchio, Micheli. IJCNN, 2010.
3. Micheli. IEEE TNN, 2009.

2. GNN/GraphESN (2009-2010)

- In GraphESN and GNN the equation are similar to RecNN
- Cycles are allowed (in state computation), the state/embedding for each v is computed iterating the state transition function until **convergence**
- Stability of the recursive encoding process is guaranteed by resorting to **contractive** state dynamics (**Banach theorem for fixed point**)
 - In *GNN* imposing constrains in the loss function (alternating learning and convergence)
 - In *GraphESN* the condition is inherited by contractivity of the reservoir dynamics (see ESP conditions): *very efficient!*



GraphESN state transitions

$$\mathbf{x}(v) = \tanh(\mathbf{W}_{in}\mathbf{u}(v) + \sum_{v' \in \mathcal{N}(v)} \hat{\mathbf{W}}\mathbf{x}(v'))$$

Context evolution, with **the iteration,
of the state for the vertex in the center**
(not just local, by *diffusion on graph*)

- Scarselli, et al. IEEE TNN, 2009
- Gallicchio, Micheli. IJCNN, 2010.

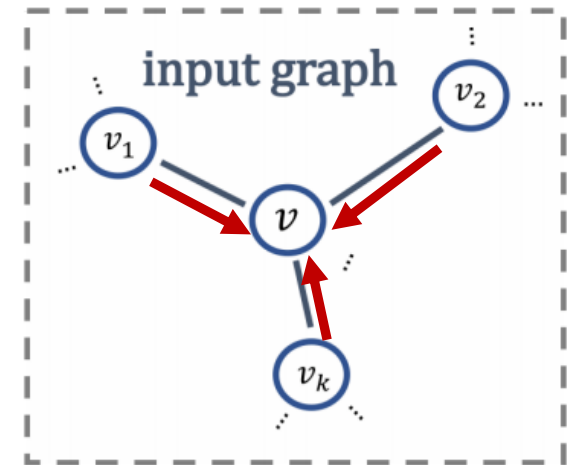
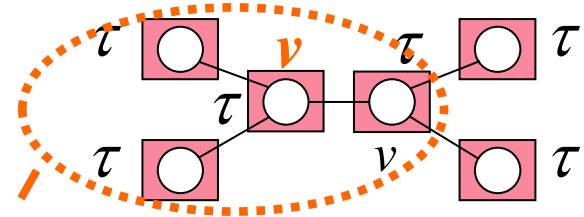
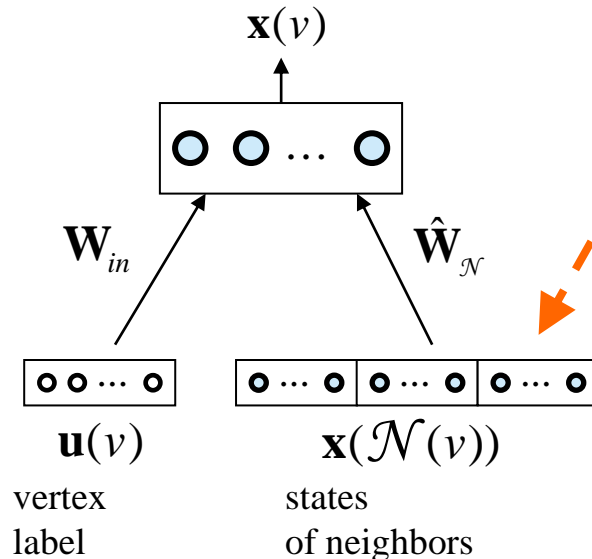
Also extended to GRU (Li et al. 2015)

2. GraphESN details (I)

Iterative (t) computation of the local encoding

$$\mathbf{x}_t(v) = \tau(\mathbf{u}(v), \mathbf{x}_{t-1}(\mathcal{N}(v)))$$

Reservoir (τ)

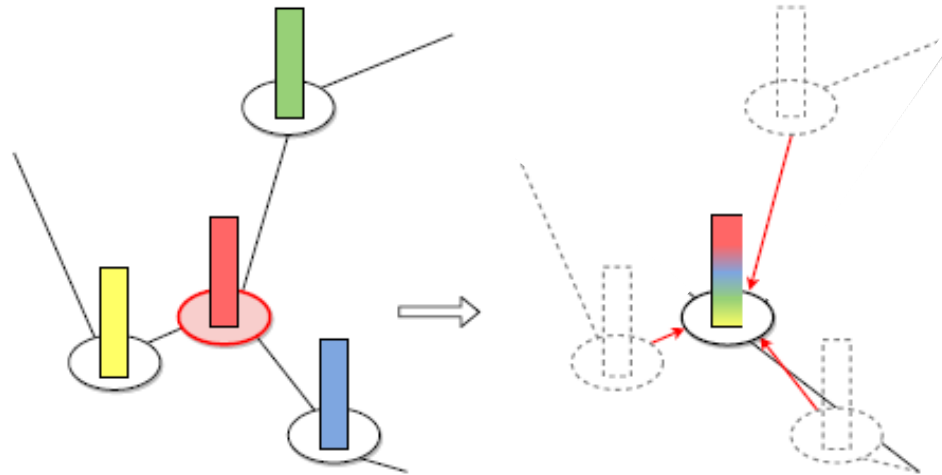


$$\mathbf{x}_t(v) = \tanh(\mathbf{W}_{in} \mathbf{u}(v) + \hat{\mathbf{W}}_{\mathcal{N}} \mathbf{x}_{t-1}(\mathcal{N}(v)))$$

A state value is computed for every vertex of each \mathbf{g}

State transition eq. (reservoir units): convergence to a fixed point

Message passing concept



After a neural message passing operation, a vertex acquires information from its neighborhood. Here 1 embedding step is shown for the central vertex, and then it can be iterated.

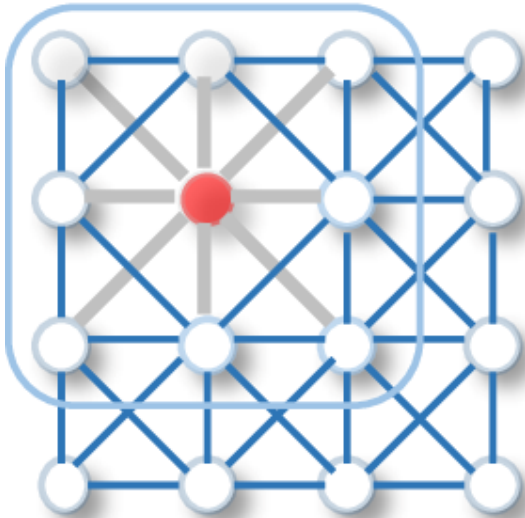
Note: this is useful for both [2. Rec.](#) and [3. Layering](#) approaches

2. GNN/GraphESN

Pro/Cons:

- + Extend the domain of RecNN to general graphs
- + Theoretical approximation capability and VC dimension have been proved
- [GNN] elongate training time with the convergence (double mutual iteration)
- Constraints of the weight values \rightarrow bias to contractive transduction
- + GraphESN dose not require training time of the recursive part \rightarrow efficient!
- + A deep (multi recurrent layers) version has been developed, called FDGNN (see the references)

Toward **3**: Layering/ Convolutional approaches: the problem



CNN: Convolutional kernel can be applied on a 2D regular grid (image matrix). The CNN takes a weighted average of the pixel values in the neighbor window. The neighbor of a vertex are ordered and have a fixed size.



CNN cannot be immediately applied:
For graphs the neighbors of a vertex are unordered and variable in size (*not Euclidian geometry*)
How to deal with it?
How to extend from local neighbor?

3. Layering

Contextual Multi-Layered approaches for graphs



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Layering basic idea:

- the mutual dependencies are managed (architecturally) through different layers (i.e. by a *deep* architecture)
 - Instead of iterating at the same layer, each vertex can take the context of the other vertices computed in the previous layers, accessing progressively to the entire graph/network
 - And each vertex takes information from all the others, including the mutual influences: **Collective inferencing**
- **NN4G** since 2005-2009 : a pioneer approach following the RecNN/ CRCC line (completely *relaxing the recursive causality assumption*)
 - In the following
- **CNN for graphs** since 2015: using the same concepts which moves the idea for 2D processing (images) to graph processing through many layers

NN4G: Motivations

Restarting from Causality

- Is it possible to find more general and simpler solutions removing *causality* without introducing cycles dependencies in the states definition ?

NN4G : Neural Network for Graphs

- Two main ingredients:
 - 1) constructive (feedforward) neural network approach
 - 2) Local and contextual information of each vertex of a graph

But recursive causality is removed

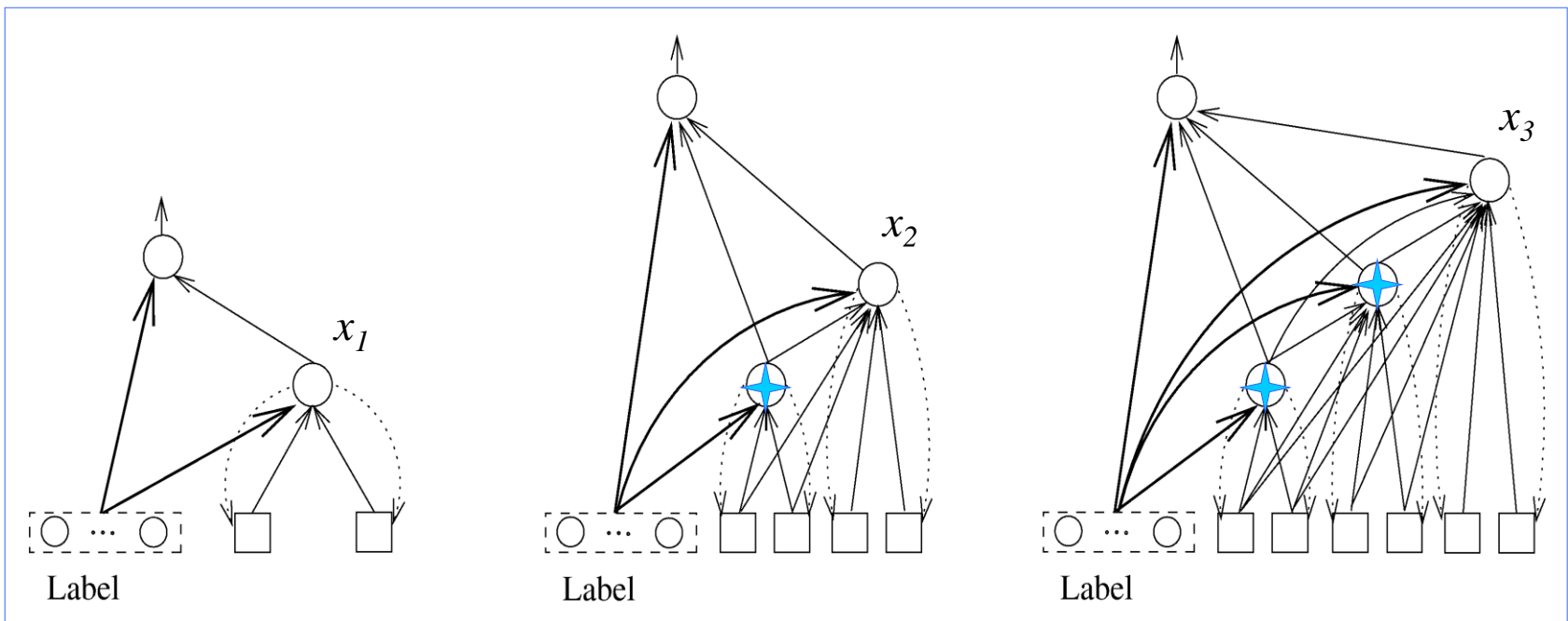
- Micheli, Sestito. WIRN 2005
- Micheli. IEEE TNN, 2009.



1) Constructive Approach

Cascade Correlation (*RecCC* in the picture):

The hidden units are progressively added to the network during training, and **frozen** after insertion

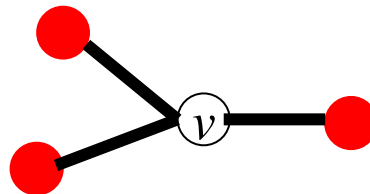


2) Local Context and Structured Domain

- We assume a fairly general class of labeled graphs $g \in \mathcal{G}$
- $Vert(g)$: set of vertices of g ; $l(v)$: label of v
- $edg(v)$: set of edges incident on v
- **Neighbors of v** :

$$N(v) = \{u \in Vert(g) \mid (u, v) \vee (v, u) \in edg(v)\} \quad \text{Directed}$$

$$N(v) = \{u \in Vert(g) \mid (u, v) \in edg(v)\} \quad \text{Undirected}$$

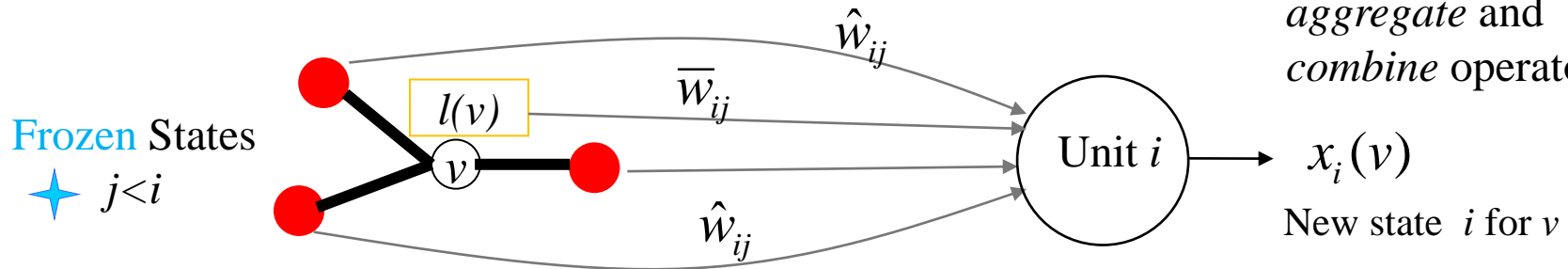


- Context of v is the set of vertices with a path to/from v affecting the output of v .

- NN4G compute a state variable for each vertex

It was the sum over the children $1..k$ for RecNN

Nowadays, called
aggregate and
combine operator



- Note: **Not Recursive** (no feedbacks): $x_i(\mathbf{v})$ depends only on frozen values ($j < i$)
 - No cyclic dependencies are introduced in the definition of the state transition system
- No topological order to follow: $x_i(\mathbf{v})$ can be computed in parallel for vertices of g

NN4G: Hidden Units Generalization (edges)



- NN4G define a very general computational framework, e.g.

$$x(v) = \begin{cases} x_1(v) = f\left(\sum_{j=0}^{L^v} \bar{w}_{1j} l_j(v)\right) \\ x_i(v) = f\left(\sum_{j=0}^{L^v} \bar{w}_{ij} l_j(v) + \sum_{j=1}^{i-1} \sum_{u \in \mathbf{N}(v)} \hat{w}_{ij}^{(v,u)} x_j(u)\right) \end{cases} \quad i = 2, \dots, N$$

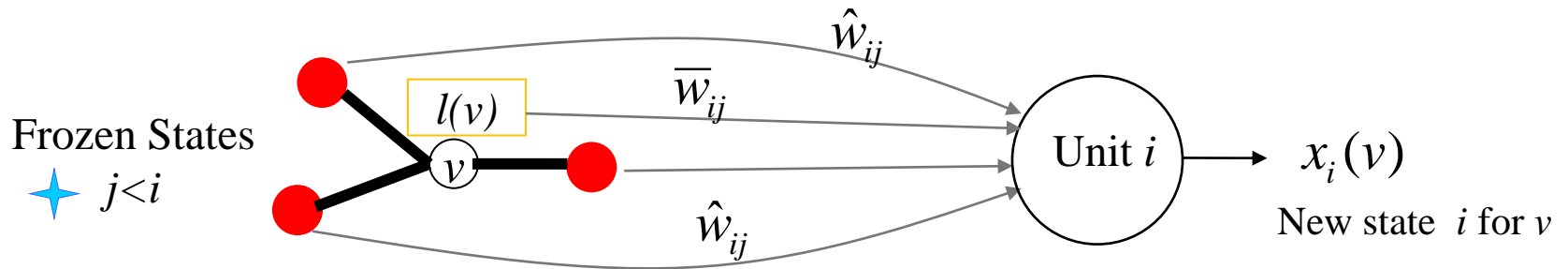
W for edge (v,u)

(Note: A red circle highlights $\hat{w}_{ij}^{(v,u)}$ in the equation, with a red arrow pointing from the box above to it.)

- (v,u) is unordered (for undirected graphs)
- **Stationarity** (weight sharing) strategy: association between weights and edges
 - Entering/leaving edges for directed graphs
 - Position for positional/ordered graphs
 - **Label of the arc** more in general: $W^{(u,v)} = W^{(t,v)}$ if $L(u,v)=L(t,v)$ (w is the same for edges sharing the same label, i.e. a different w for each different edge type)
- First trials: full stationarity: 1 weights for each edges:
 - unordered and undirectd graphs and
 - strong parameters reduction

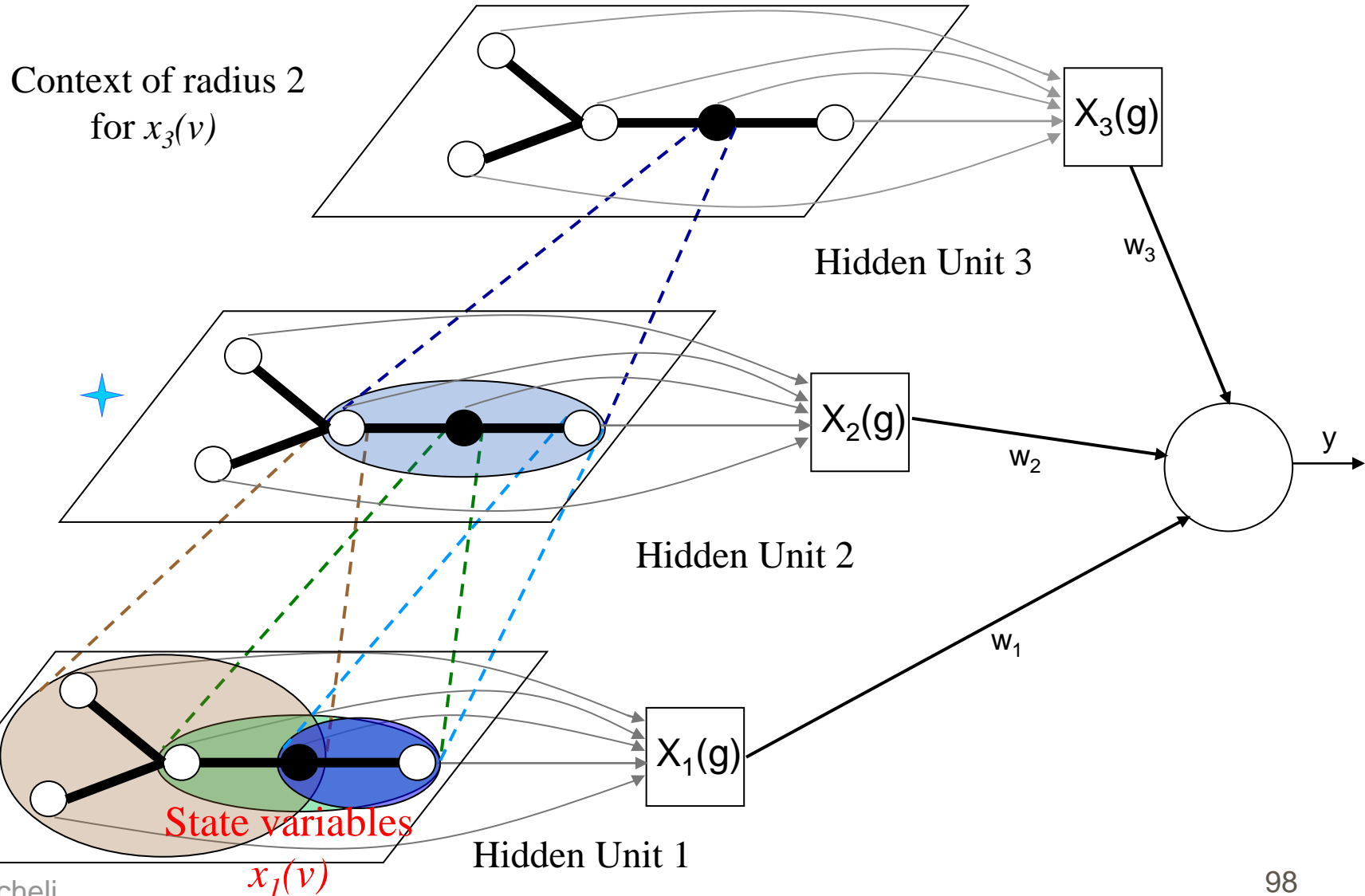
NN4G: 2) Hidden Units and Context

- Is NN4G just a relational approach taking only a local neighborhood (for each hidden unit) ?



- No**, because through layering NN4G extends the context of each vertex to all the vertices in graph
- Because progressively, **by composition**, the model extends the context of influence to other vertices through the context developed in the previous (frozen) hidden units (layers) → *see the next slide*

Evolution of the Context (Compositional)

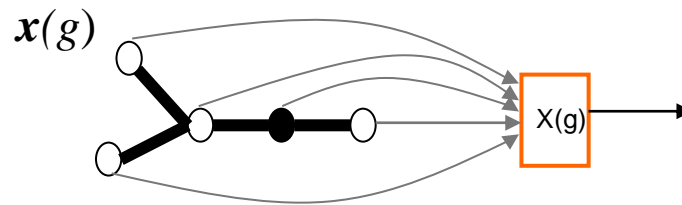


NN4G: Output unit

(nowadays *readout pooling*)

1. From states to the output layer
 - IO- isomorphic transduction (an output for each vertex) or
 - A scalar value for a whole graph can be emitted, using an operator X , e.g.:

States mapping
function



It can be a simple permutation invariant function
e.g. a simple global sum or average or a selection from relevant vertices etc.

2. Output layer: e.g. A single standard neural unit

$$y(g) = f\left(\sum_{j=0}^N w_j X_j(g)\right)$$

- **Learning:** as in (feedforward) Cascade Correlation: adding hidden units and interleaving min. of error at the output layer and max. of the correlation score for each hidden unit.

Summary: NN4G Algorithm

(compute the output for a set of graphs)



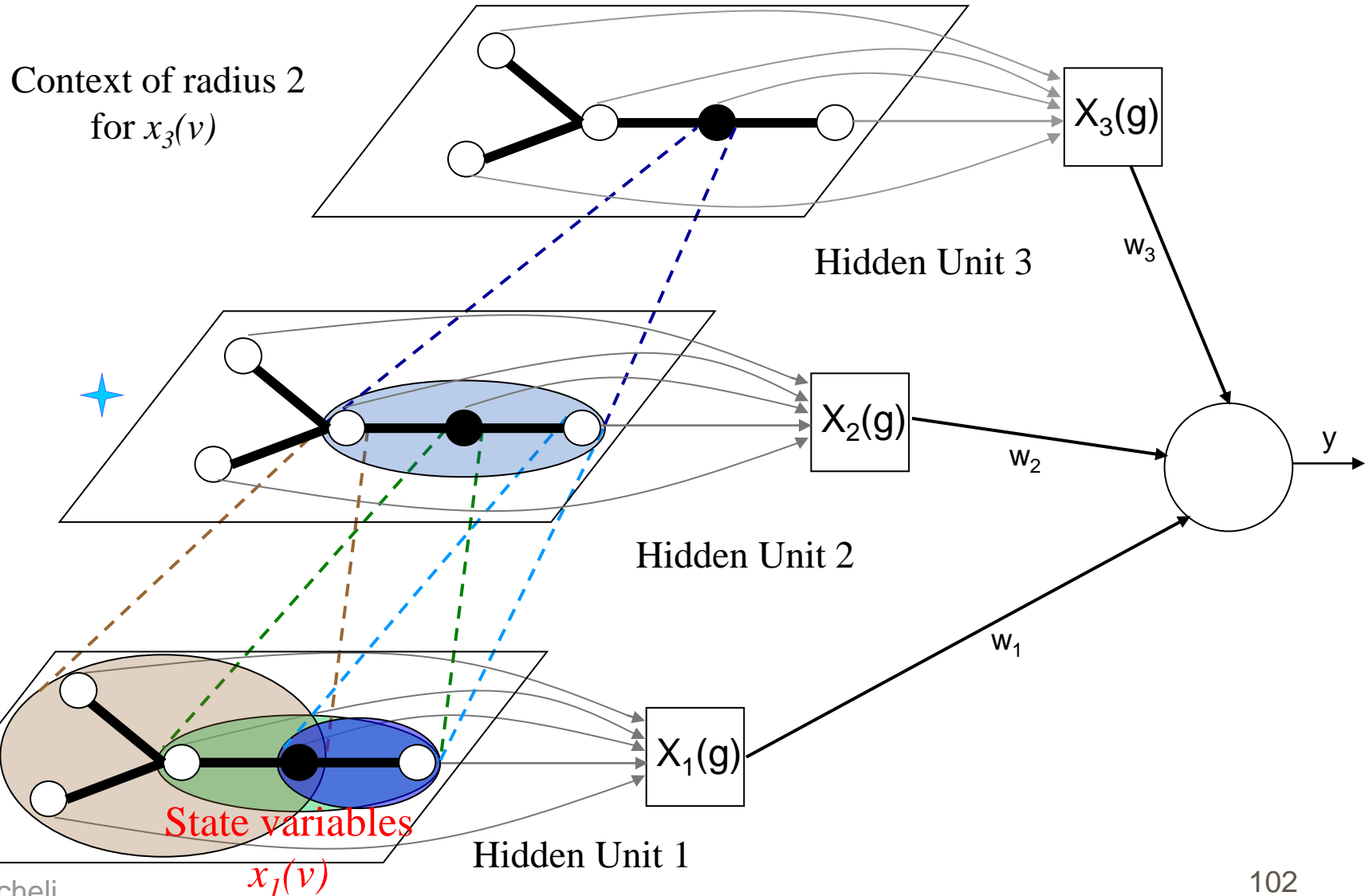
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1. For $i=1$ to N
2. For all g in G
3. For all v in $Vert(g)$
4. Compute $x_i(v)$ (even in parallel *)
5. Compute $X_i(g)$
6. For all g in G
7. Compute $y(g)$

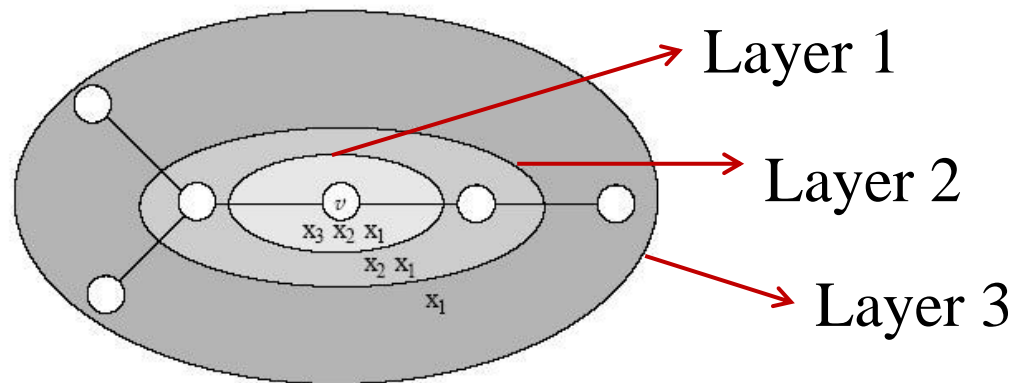
(*) I.e. a traversal of the input graph: the result does not depend on the visiting order
Weight sharing: the same model is applied for each vertex

Evolution of the Context (Compositional)



NN4G: Context Growth

- The growth of the context is symmetric in each direction starting from each vertex, and grow with layers



- In such a way, the size of the context window can grow and we do not need to fix it prior to learning.
- The **depth** of networks is functional to context development*

Context Scope:

Formal Properties relating h and C



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- It has been **formally proved** that that the context $C(x_h(v))$ grows one step ahead, for each added unit (layer h), as $N^h(v)$:
 - the dimension of the context is proportional to the number of units,
 - and the structure of the composition is given by the topology of the input graph
- And that $C(x_h(v))$ can involve all the vertices of the graph:

Theorem [NN4G]: Given a finite size graph G , there exists a finite number h of state variables (hidden layers) such that for each v in G the context of v involves all the vertices of G .

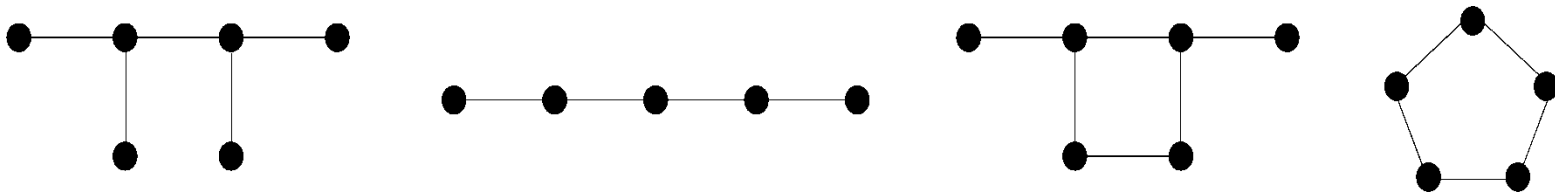
- In particular, $h > \text{"diameter"}$ of the graph satisfy the proposition.

Micheli. IEEE TNN, 2009.



Example of experimental assesment: Cyclic versus Acyclic Undirected Graphs

- Artificial task: test NN4G capability to learn a relevant topological feature, i.e the **occurrence of cycles** in the input undirected graphs, which cannot be directly treated by RNN.
- **Input domain:** 150 cyclic graphs and 150 acyclic graphs with 3 up to 10 vertices (total 2670 vertices)



- **100% test classification accuracy** over all the folds of 10-fold cross-validation with 5 trials for each fold.
- Just **2 hidden units**.
- In fact, the second unit is able to distinguish the ratio between the number of edges and vertices in the graph, which is a sufficient feature to discriminate the input graphs on the basis of the occurrence of cycles in its topology.

NN4G Recap

- NN4G: *A deep model for graphs*
- Characteristics:
 - Direct/undirected cyclic/acyclic labeled graphs
 - W.r.t. RecNN does not assume **causality** over directed structure; in particular, no assumption on the topological order is needed;
 - ☆ — Incremental, layer by layer learning & automatic model design
 - **Depth** functional to contextual encoding: Dimension of context grows with layers (*formally proved*)
 - ☆ — **Efficient**: no cyclic def. of state var., divide et impera on the task
 - Scaling: Current model (full stationarity): $O(|G|Vh^2 \text{ epochs})$: Linear in the number V of vertices
 - ☆ — Generality: No constraints on weights values (vs GNN)
 - Pool strategy (in cascade corr. training): local minima avoidance, supervised architecture optimization

A first comparison NN4G / Conv.NN for Graphs

Concepts in common:

- Traversal of the input graph: Visiting (the nodes of) input graphs through units with weight sharing (stationarity)
 - This corresponds for CNN to the convolution over (the nodes of) input graphs,
 - i.e. constrained to graph topology instead of 2D matrix
- Layering and hence *moving to deep architecture* (functional to *contextual processing*)
- Composition for the (no causal) context learning, parsimony, and adaptivity are achieved and extend to *any kind of graphs*
- Node-centric learning can exploit the Collective inference

A first comparison

NN4G / Conv.NN for Graphs

Main differences are more related to the *training*:

- **CNN-Gs** typically use CNN architecture/training approaches,
 - Fixed architecture (few hidden layers)
 - Top-down back-prop (end-to-end): can be quite computational demanding using many layers
- **NN4G**: Incremental, layer by layer learning & automatic model design
 - Advantages: No gradient vanish issue, *divide et impera*, automatic number of layers, etc.

Many models and variations ...

Differences among Convolutional models e.g. for:

- Neighbors aggregation (or other slight variations)
 - E.g. NN4G, GCN, DCNN, PATCHY-SAN, GIN, ECC, GAT, ...
also with sampling, e.g. FastGCN, GraphSAGE, ...
- Different filters for spectral approaches
 - E.g. SpectralCNN, ChebNet, ARMA-GCN, ...
- Pooling among layers, including decimation of graph nodes and pyramidal schemas
 - E.g. Graclus, DiffPool, NDP, ...
- Hybrid models

Learning in Structured Domain

Plan in 2 lectures

1. Recurrent and Recursive Neural Networks

Extensions of models for supervised and unsupervised learning in structured domains

- Extensions of models for learning in structured domains
- Motivation and examples (structured data)
- The structured data (recursive)
- Recursive models: RNN and RecNN
- Recursive Cascade Correlation & other recursive approaches

2. Moving to DPAG and Graphs: the role of causality

- Recap SD1
- Causality for Recurrent and Recursive models &
- Contextual approaches (CRCC and DPAGs)
- Neural Networks for graphs
- **Other models and looking ahead**

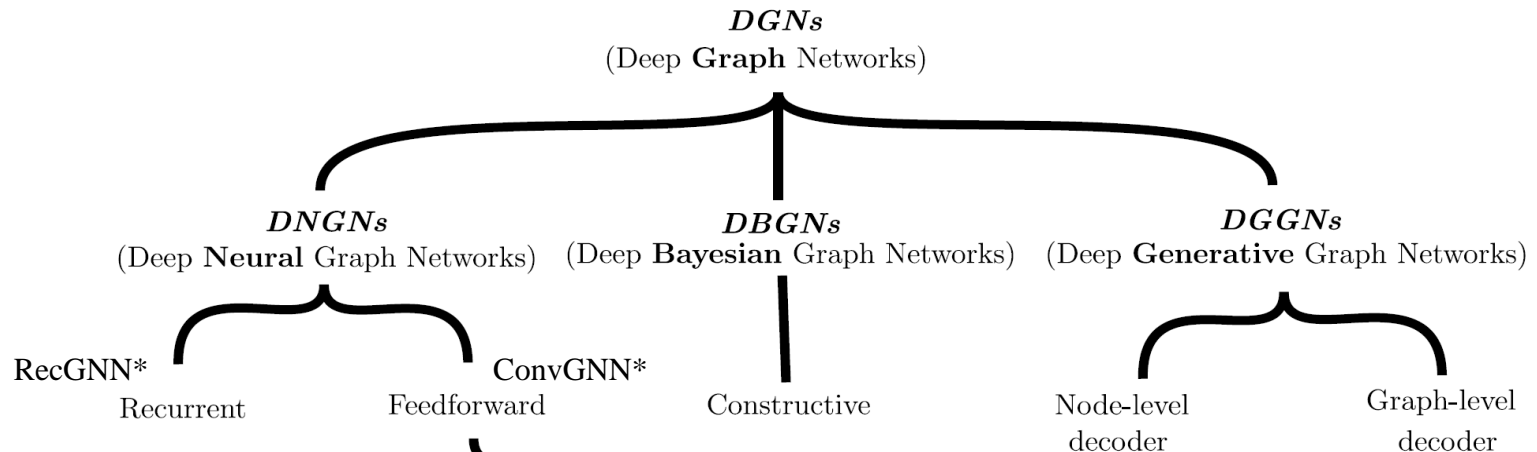
By a journey through the causality assumption!

Terminology again (recap)

See lect. SD1: Deep learning for graphs: (deep) NN for/on graphs (NN4G/**DNNG**), graph NN (**GNN**), graph convolutional networks (**GCN**), Graph nets, ...

In particular:

- **RecGNN*** → the recursive approach (e.g. originally GNN and GraphESN)
- **ConvGNN*** → for spectral-based approaches and the spatial-based approaches (e.g. NN4G and all the convolutional approaches)
- **DGN*** → An extend class to include also Bayesian and Generative approaches



* A Comprehensive Survey on Graph Neural Networks – TNNLS Jan. 2021

** A gentle introduction to deep learning for graphs – Neural Networks Sep. 2020

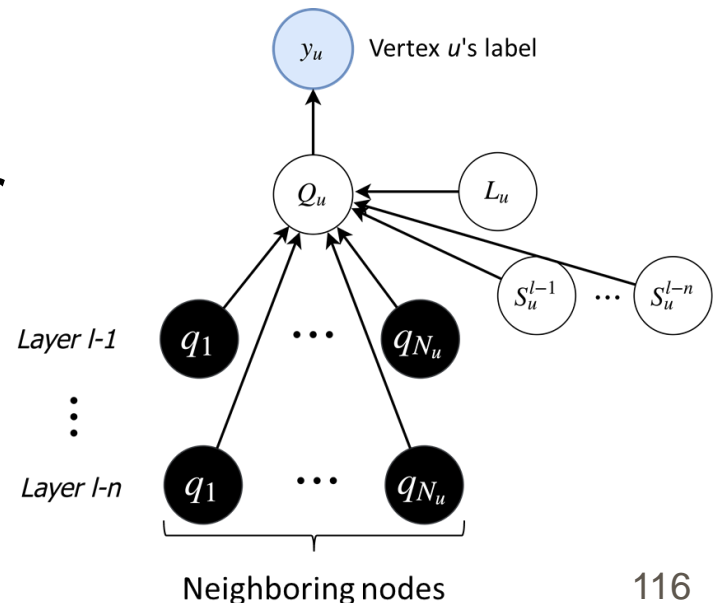
DBGN: by NN4G+ HTMM

- We can extend the contextual ideas also to RC and HTMM approaches making them deep and for graphs
- E.g. ICML 2018 A NN4G realized by a *generative* approach (a DBGN)
- trained by a mix of unsupervised (Markov models for hidden layer) and supervised (output layer) approaches
- Also for unsupervised / semi-supervised probabilistic learning

- *Contextual Graph Markov Models*

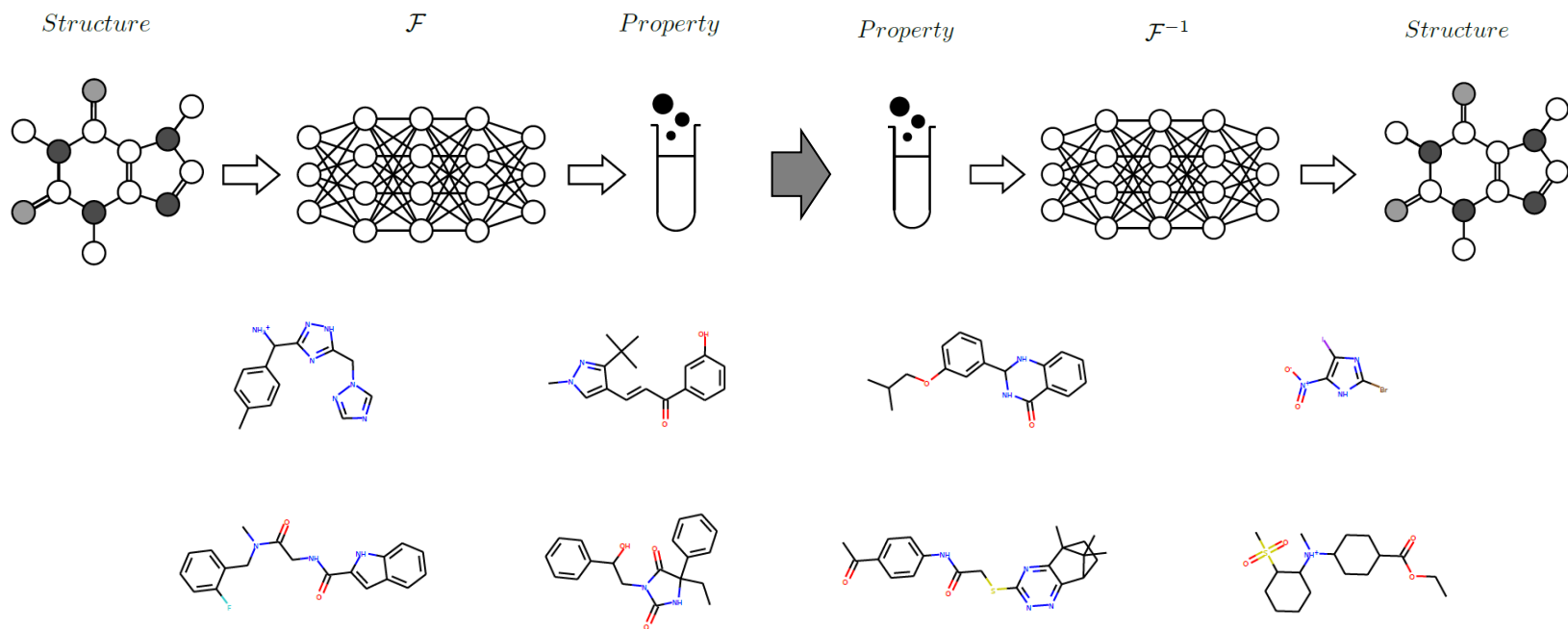
Bacciu , Errica, Micheli, ICML 2018

Bacciu , Errica, Micheli, JMLR 2020



Generative Graph Networks

- **Generative:** NN for graphs can learn how to generate new data preserving the statistical properties of the training set → generate new graphs



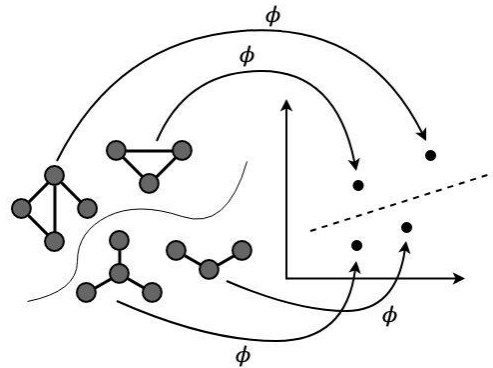
Podda, Bacciu, Micheli. A Deep Generative Model for
Fragment-Based Molecule Generation - AISTATS (2020)

Further discussion: properties

- **Models for graphs** support different graph structures as well as a flexible representations of global, node, and edge attributes, customizable according to specific demands of tasks.
- **Non-Euclidean geometry**: they treat directly the structured nature of graphs
- **Modularity and compositionality**: they can learn independent mechanisms that can be reused in several parts of the graph.
- **Cross-modality**: they can learn how to combine structured unstructured data sources. This is particularly relevant when integrating data/signals at different levels of complexity.
- **Multiscale**: the graph representation has the capability of integrating granular information organized as networks at different layers of complexity.
 - E.g. patterns in higher-order structures such as motifs, pathways, tissues (as compositions of cells), organs (as composition of tissues), processes and apparatus (as composition of organs), stratification (as composition of individuals).

And Kernels?

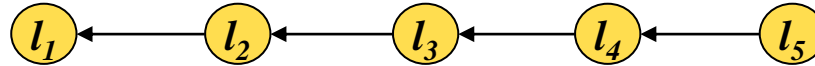
- Large set of proposals (out of the scope)
- Examples of kernels for SD from RC [1] and HTMM [2] for SD, e.g. (by CIML):
- Kernels for SD from RC
 1. D. Bacciu, C. Gallicchio, A. Micheli, *A reservoir activation kernel for trees*. ESANN 2016
- Kernels for SD from HTMM (adaptive kernels + generative & discriminative)
 2. D. Bacciu, A. Micheli, A. Sperduti. *Generative Kernels for Tree-Structured Data*, IEEE TNNLS (Transactions on Neural Networks and Learning Systems), 2018



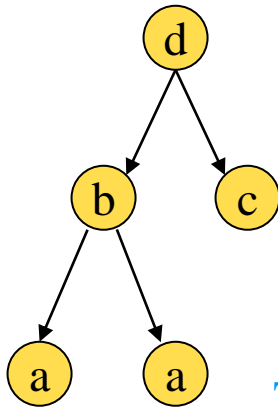
Summarizing the MODELS panorama for SD (examples)



Standard ML models for
flat data

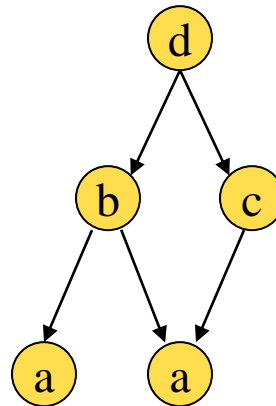


- Recurrent NN/ESN
- HMM
- Kernel for strings ...



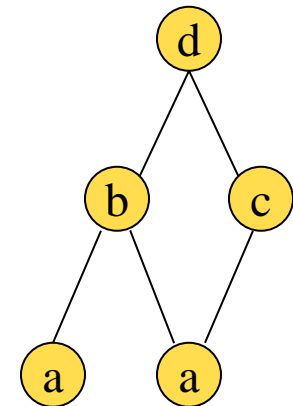
Tree:

- Recursive NN
- Tree ESN
- HTMM
- Tree Kernels
- ...



DPAG:

- CRCC



- GNN/GraphESN
- NN4G, CGN
- DGN
- Graph Kernels
- SRL
- ...

See references for models in the bibliography slides (later)

Software

- PyTorch geometric  PyTorch
geometric

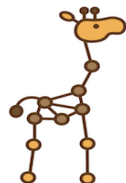
- DGL (agnostic: PyTorch, TensorFlow or MXNet)



- Spektral (TF)



- Jraph (in jax)



- ...

- In CIML (Software): PyDGN



Data Sets: Large Collections

- OGB (Stanford)



- TUDataset (TU-Dortmund - ICML 2020)



- inside PyTorch geometric and the other tools



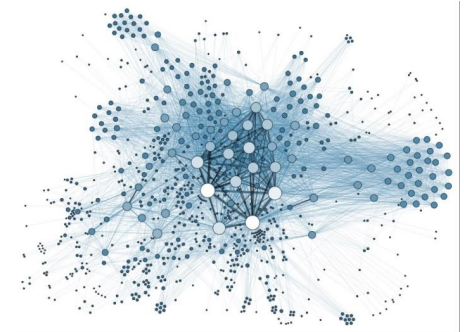
Future – just ahead

- **New models for SD**
(discussed so far)
- **New applications**
- ...



Applications

- See the first lecture SD1 (initial slides) for examples for molecules, social, biological networks, maps
 - And also recommendation systems (Amazon!), image processing, games, medical records, ...
 - But *all the data* have relationships !!!
-
- Let me introduce some running projects in CIML

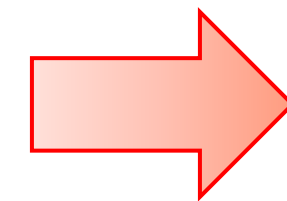
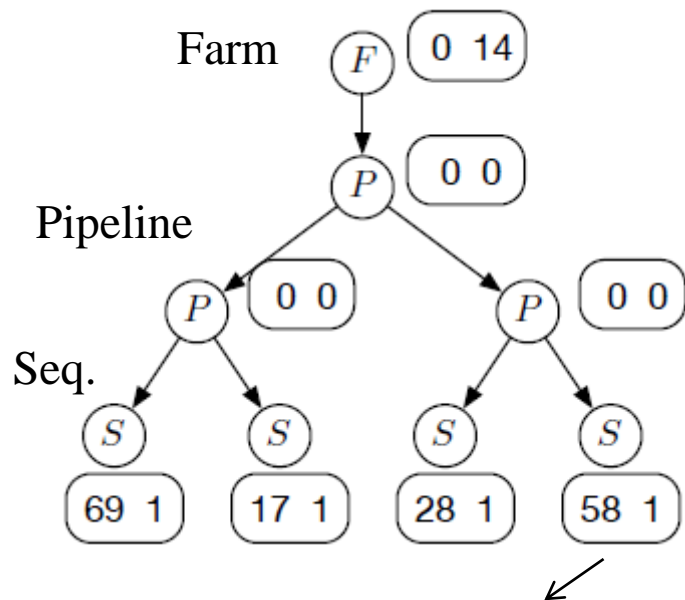


**Computational Intelligence &
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SDL for parallel computing

- Mapping and configuration problem in *parallel computing* (on **tree** data representations): estimation of execution time and energy [with M. Danelutto, UNIFI]

Skeleton application description



Execution time (sec) or
Energy consumption

NN for Trees

On going: Thesis available!

Cybersecurity and Trustworthy

Under construction (with ISTI CNR):

- Starting for example from malware detection/classification from a «call graph» or «control flow graph» of the code
- Also ... toward trustworthy learning for graphs (a new field!)



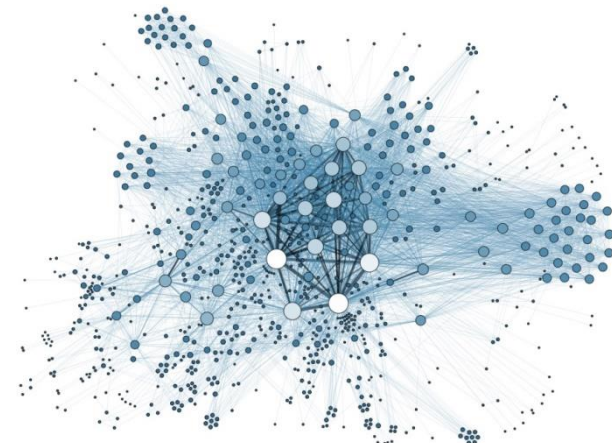
Bioinformatics

Under construction! Ready to apply for **tree/graph data** on:

- System biology (graphs/networks) (with P. Milazzo) → next slides
- Bioinformatics:
 - Prediction of proteins function → next slides
 - Pan-genome analysis (by graph representation)
 - Coarse grained models for proteins → next slides
 - Bio-molecular Networks → next slides
 - Coarse grained models for Proteins → next slides



On going: Thesis available!

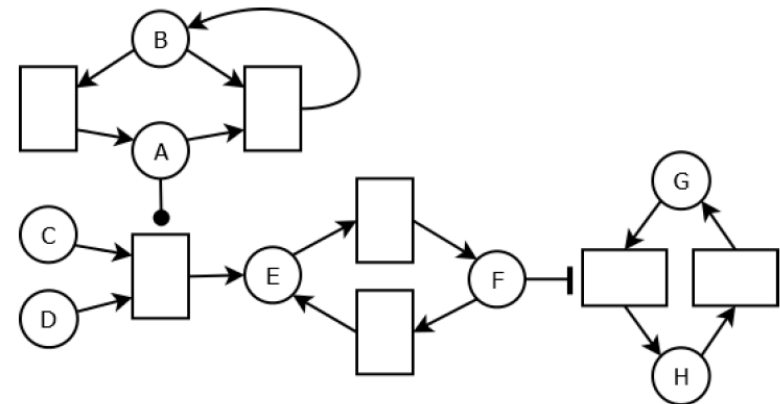


Classification of Biochemical Pathway Robustness with Neural Networks for Graphs



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- **Biochemical Pathways (BPs)** are sets of chemical reactions among biomolecules
- They model **cell functionality**
- Structure described by **graphs** (e.g. **Petri Nets**), dynamical properties analyzed with Ordinary Differential Equations (ODEs)
- Entities (**nodes**): species (circle) or reactions (square)
Relations (**arcs**): produce, enhance, block
 - there are also Input/Output nodes: induced sub-graphs of paths for different I/O nodes

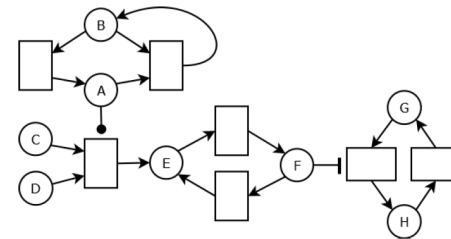


UNIFI funded research project - PRA 2020
METODI INFORMATICI INTEGRATI PER LA BIOMEDICA

Classification of Biochemical Pathway Robustness with Neural Networks for Graphs

- **Input:** Pathway Petri nets (their correspondent **directed** graph), for each pair of species in a given net
- **Output:** an associated **robustness** value (0/1)
- Direct prediction for the Petri nets topology, avoiding costly ODE simulations
- Does the networks include enough information to predict robustness? Or other properties?

On going: Thesis available!



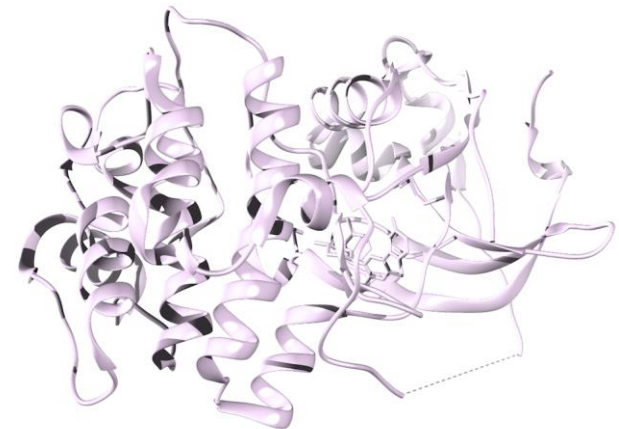
- **Best paper award @ BIOSTEC-BIOINFORMATICS 2020**
 - Bove, P.; Micheli, A.; Milazzo, P. and Podda, M. (2020). Prediction of Dynamical Properties of Biochemical Pathways with Graph Neural Networks. In Proceedings of the 13th International Joint Conference on Biomedical Engineering Systems and Technologies - Volume 3: BIOINFORMATICS, pages 32-43

Prediction of proteins function

- Prediction of proteins function
- Using gene ontology graphs
- Possibility to participate to CAFA challenge
 - There are many proteins in the databases for which the sequence is known, but the function is not.
 - The Critical Assessment of Functional Annotation (CAFA) is an ongoing, global, community-driven effort to evaluate and improve the computational annotation of protein function.

Approaches can include:

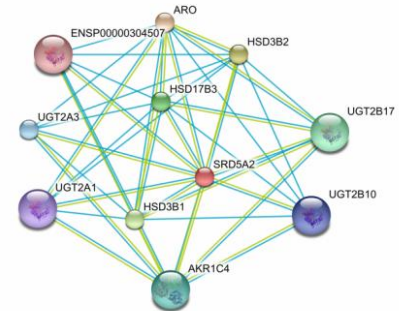
- SVM/Kernel building by efficient computation of common sub-graphs between pairs of proteins (with R. Grossi)
- Use of NN for graphs



Bio-molecular Networks

A Bio-molecular network is a graph representation of

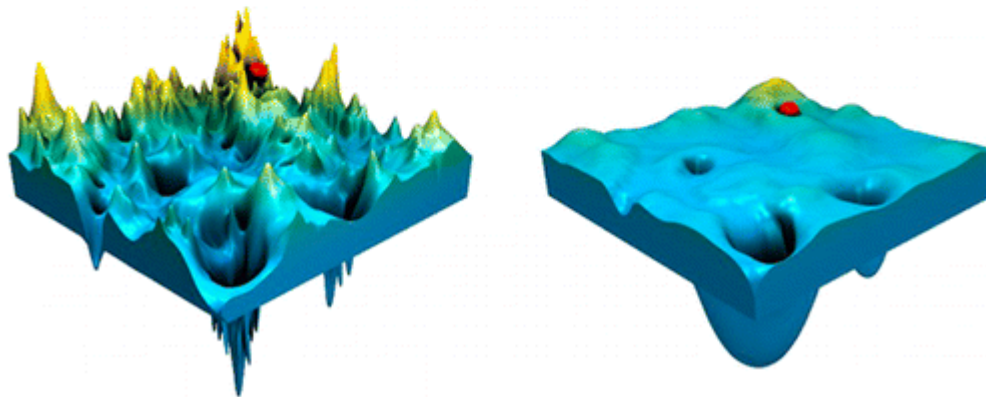
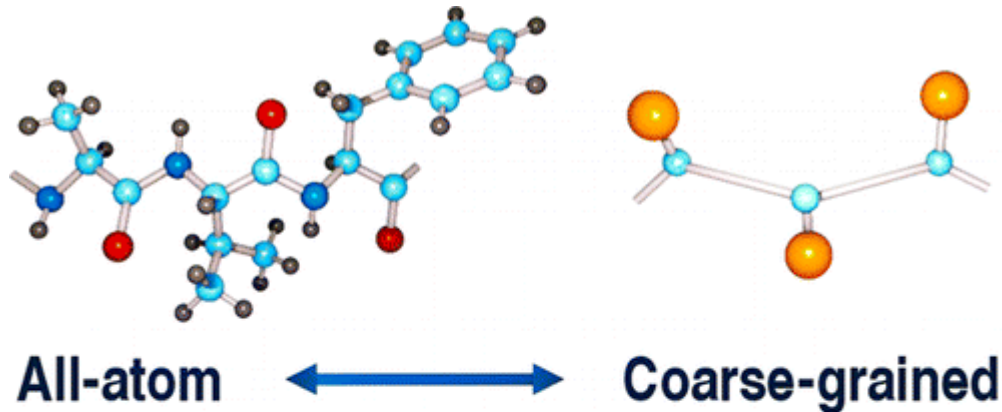
- **Relationships** (of which there are many types) amongst a group of biomolecules.
- **Vertices** or nodes represent biomolecules, including macromolecules such as genes, **proteins**, and RNAs, or small biomolecules like amino acids, sugars, and nucleic acids



In particular, other networks data/problems to extend the application of ML/NN for graphs are:

- Proteins (interactions or similarities or ontologies) networks for drug or oncology research (with other insitutes)
 - These graphs contain a relevant information that can be exploited for conducting different kinds of analysis, such as automatic function prediction, disease gene prioritization, drug repositioning or discovery, etc.
- Knowledge graphs for COVID related analysis (with Univ. of Padova, under construction)

Coarse grained models for Proteins (Biophysics with Univ. of Trento)



By NN for graphs!

On-going: Thesis available!

A more general aim (CIML -Pisa)



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- Adaptive processing of SD
- **A theoretical and practical framework for the automatic design of *efficient* models** for sequences, trees and graphs (both generative and discriminative) exploiting DL approaches
 - Able to answer the main issue of DL frameworks: how many layers? How many units? Which hyper.? Etc.
 - Open to *semi-supervised* learning and different graph and network tasks
 - *Efficient* by incremental NN and RC approaches



**Computational Intelligence &
Machine Learning Group**



Bibliography: aims

Different parts in the following:

- Basic/Fundamentals
- To go ahead
 - Many topics can be subject of study and development
 - Many many works in literature (arrive continuously)!
 - Many possible topics for demand and possible thesis
 - **More bibliography on demand:** micheli@di.unipi.it

Bibliografia (Basic, origins of RecNN)



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RecNN

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* TreeESN: efficient RecNN

- C. Gallicchio, A. Micheli.
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Deep Reservoir Neural Networks for Trees. Information Sciences 480, 174-193, 2019.

* HTMM: further developments (generative)

- D. Bacciu, A. Micheli and A. Sperduti.
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