

Introduction to Signal Processing

Davide Bacciu

Dipartimento di Informatica
Università di Pisa
bacciu@di.unipi.it

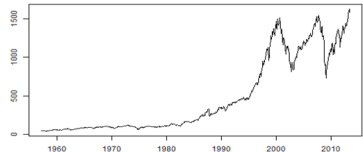
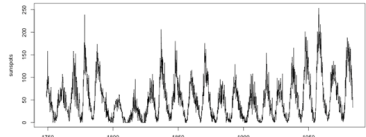
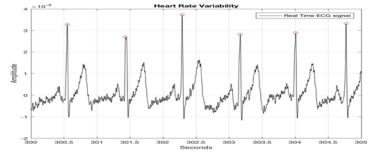
Intelligent Systems for Pattern Recognition



Signals = Time series

A sequence of measurements in time

- Medicine
- Financial
- Meteorology
- Geology
- Biometrics
- Robotics
- IoT
- Biometrics
- ...



Formalization

A time series \mathbf{x} is a sequence of measurements in time t

$$\mathbf{x} = x_0, x_1, \dots, x_t, \dots, x_N$$

where x_t (or $x(t)$) is the measurement at time t .

- Observations can be observable at **irregular** time intervals
- Time series analysis assumes **weakly stationary** (or second-order stationary) data
 - $\mathbb{E}[x_t] = \mu$ for all t
 - $\text{Cov}(x_{t+\tau}, x_t) = \gamma_\tau$ for all t (γ does only depend on lag τ)

Goals

- **Description** - Summary statistics, graphs
- **Analysis** - Identify and describe dependencies in data
- **Prediction** - Forecast the next values given information up to time t
- **Control** - Adjust the parameters of the generative process to make the time series fit a target

The goal of this lecture is providing knowledge on some basic techniques that can be useful as

- Baseline
- Preprocessing
- Building blocks

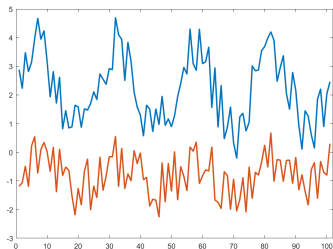
Key Methods

- **Time** domain analysis - Assesses how a signal changes over time
 - Correlation and Convolution
 - Autoregressive models
- **Spectral** domain analysis - Assesses the distribution of the signal over a range of frequencies
 - Fourier Analysis
 - Wavelets

Mean and Autocovariance

Some interesting **estimators** for time series statistics are
Sample mean

$$\hat{\mu} = \frac{1}{N} \sum_{t=1}^N x_t$$



Autocovariance for lag $-N \leq \tau \leq N$

$$\hat{\gamma}_{\mathbf{x}}(\tau) = \frac{1}{N} \sum_{t=1}^{N-|\tau|} (x_{t-\tau} - \hat{\mu})(x_t - \hat{\mu})$$

Autocorrelation

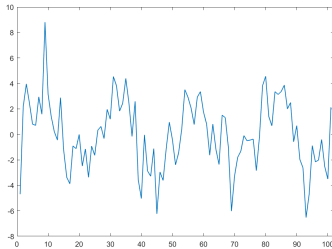
Autocovariance serves to compute **autocorrelation**, i.e. the correlation of a signal with itself

$$\hat{\rho}_{\mathbf{x}}(\tau) = \frac{\hat{\gamma}_{\mathbf{x}}(\tau)}{\hat{\gamma}_{\mathbf{x}}(0)}$$

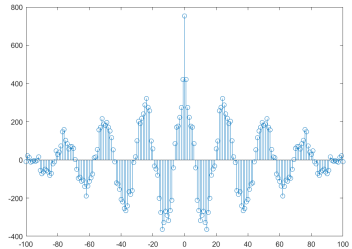
Autocorrelation analysis can reveal **repeating patterns** such as the presence of a periodic signal hidden by noise

Autocorrelation Plot

A revealing view on timeseries statistics



What do you see in this time series?



Autocorrelogram reveals a sine wave

Cross-Correlation (Discrete)

A **measure of similarity** of \mathbf{x}^1 and \mathbf{x}^2 as a function of a time lag τ

$$\phi_{\mathbf{x}^1 \mathbf{x}^2}(\tau) = \sum_{t=\max\{0, \tau\}}^{\min\{(T^1-1+\tau), (T^2-1)\}} \mathbf{x}^1(t-\tau) \cdot \mathbf{x}^2(t)$$

- $\tau \in [-(T^1 - 1), \dots, 0, \dots, (T^1 - 1)]$
- The maximum $\phi_{\mathbf{x}^1 \mathbf{x}^2}(\tau)$ w.r.t. τ **identifies the displacement** of \mathbf{x}^1 vs \mathbf{x}^2

Cross-Correlation (Discrete)

Normalized cross-correlation returns an amplitude independent value

$$\bar{\phi}_{\mathbf{x}^1\mathbf{x}^2}(\tau) = \frac{\phi_{\mathbf{x}^1\mathbf{x}^2}(\tau)}{\sqrt{\sum_{t=0}^{T^1-1} (x^1(t))^2 \sum_{t=0}^{T^2-1} (x^2(t))^2}} \in [-1, +1]$$

- $\bar{\phi}_{\mathbf{x}^1\mathbf{x}^2}(\tau) = +1 \Rightarrow$ The two time-series have the **exact same shape** if aligned at time τ
- $\bar{\phi}_{\mathbf{x}^1\mathbf{x}^2}(\tau) = -1 \Rightarrow$ The two time-series have the exact same shape but **opposite sign** if aligned at time τ
- $\bar{\phi}_{\mathbf{x}^1\mathbf{x}^2}(\tau) = 0 \Rightarrow$ Completely **uncorrelated signals**

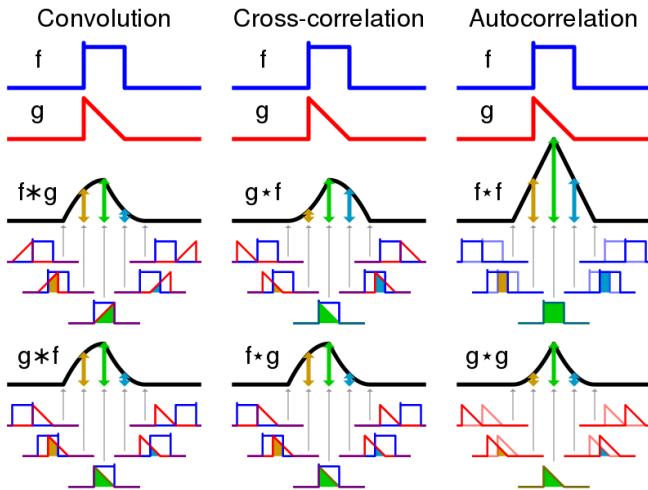
Cross-Correlation - Something already seen...

What is this?

$$(f * g)[n] = \sum_{t=-M}^M f(n-t)g(t)$$

- Discrete convolution on finite support $[-M, +M]$
- Similar to cross-correlation but **one of the signals is reversed** (i.e. $-t$ in place of t)
- Convolution can be seen as a **smoothing** operator (commutative!)

A View of Time Domain Operators



Autoregressive Process

A timeseries **Autoregressive process (AR)** of order K is the linear system

$$x_t = \sum_{k=1}^K \alpha_k x_{t-k} + \epsilon_t$$

- Autoregressive $\Rightarrow x_t$ regresses on itself
- $\alpha_k \Rightarrow$ **linear** coefficients s.t. $|\alpha| < 1$
- $\epsilon_t \Rightarrow$ sequence of i.i.d. values with mean 0 and fixed variance

ARMA

Autoregressive with Moving Average process (ARMA)

$$x_t = \sum_{k=1}^K \alpha_k x_{t-k} + \sum_{q=0}^Q \beta_q \epsilon_{t-q}$$

- $\epsilon_t \Rightarrow$ Random white noise (again)
- The current timeseries value is the result of a regression on its past values plus a term that depends on a combination of stochastically uncorrelated information
- Accounts for innovations or spikes in the data

Estimating Autoregressive Models

- Need to estimate
 - The values of the linear coefficients α_t (and β_t)
 - The order of the autoregressor K (and Q)
- Estimation of the α is performed with the **Levinson-Durbin recursion**, e.g. in Matlab `a = levinson(x, K)`
- The order is often estimated with a **Bayesian model selection** criterion, e.g. BIC, AIC, etc.

The set of autoregressive parameters $\alpha_1^i, \dots, \alpha_K^i$ fitted to a specific timeseries \mathbf{x}^i is used to confront it with other timeseries

Comparing Timeseries by AR

- Timeseries **clustering**

$$d(\mathbf{x}^1, \mathbf{x}^2) = \|\alpha^1 - \alpha^2\|_M^2$$

- **Novelty/anomaly** detection

$$\text{Test } Err(x_t, \hat{x}_t) < \xi$$

where \hat{x}_t is the AR predicted value

- Encode time series as a set of α^j vectors and feed them to a **flat ML model**

Spectral Analysis

Analysing time series in the **frequency domain**

Key Idea

Decompose a time series into a linear combination of sinusoids (and cosines) with random and uncorrelated coefficients

- **Time domain** - Regression on past values of the time series
- **Frequency domain** - Regression on sinusoids

Use the framework of Fourier Analysis

Fourier Transform

- Discrete Fourier transform (DFT)
- Transforms a time series from the time domain to the frequency domain
- Can be easily **inverted** (back to the time domain)
- Useful to **handle periodicity** in the time series
 - Seasonal trends
 - Cyclic processes

Representing Functions

We (should) know that, given an **orthonormal** system $\{\mathbf{e}_1; \mathbf{e}_2, \dots\}$ for E , we can represent any function $f \in E$ by a linear combination of the basis

$$\sum_{k=1}^{\infty} \langle f, \mathbf{e}_k \rangle \mathbf{e}_k.$$

Given the orthonormal system

$$\left\{ \frac{1}{\sqrt{2}}, \sin(x), \cos(x), \sin(2x), \cos(2x), \dots \right\}$$

the linear combination above becomes the **Fourier Series**

$$a_0/2 + \sum_{k=1}^{\infty} [a_k \cos(kx) + b_k \sin(kx)]$$

with a_k, b_k being **coefficients** resulting from integrating $f(x)$ with the sin and cos functions

Representing Functions in Complex Space

Using $\cos(kx) - i \sin(kx) = e^{-ikx}$ with $i = \sqrt{-1}$ we can rewrite the Fourier series as

$$\sum_{k=-\infty}^{\infty} c_k e^{ikx}$$

on the orthonormal system

$$\{1, e^{ix}, e^{-ix}, e^{i2x}, e^{-i2x}, \dots\}$$

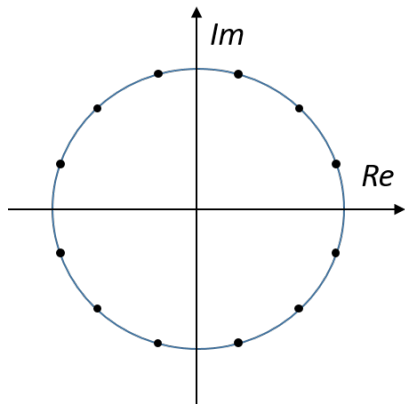
and c_k integrates $f(x)$ with e^{-ikx} .

Representing Discrete Time series

- 1 Consider a discrete time series $\mathbf{x} = x_0, x_1, \dots, x_{N-1}$ of length N and $x_n \in \mathbb{R}$
- 2 Using the exponential formulation the orthonormal system is made of $\{\mathbf{e}_0, \mathbf{e}_1, \dots, \mathbf{e}_{N-1}\}$ vectors $\mathbf{e}_k \in \mathbb{C}^N$
- 3 The n -th component of the k -th vector is

$$[\mathbf{e}_k]_n = e^{-\frac{2\pi ink}{N}}$$

Graphically



A basis \mathbf{e}_k at frequency k has N elements sampled from the **roots of the unitary circle** in imaginary-real space

Discrete Fourier Transform

Given a time series $\mathbf{x} = x_0, x_1, \dots, x_{N-1}$ its **Discrete Fourier Transform** (DFT) is the sequence (in frequency domain)

$$X_k = \sum_{n=0}^{N-1} x_n e^{-\frac{2\pi ink}{N}}$$

The DFT has an **inverse transform**

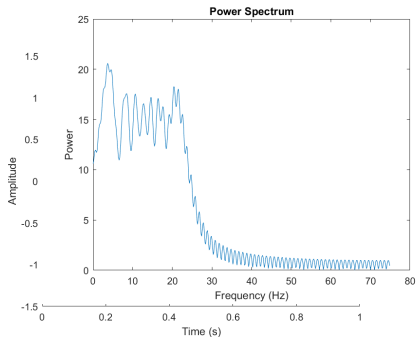
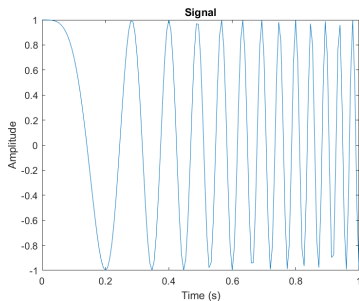
$$x_n = \frac{1}{N} \sum_{k=0}^{N-1} X_k e^{\frac{2\pi ink}{N}}$$

to go back to the time domain.

Amplitude

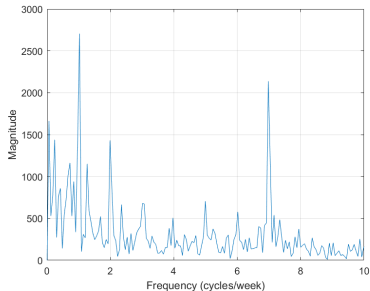
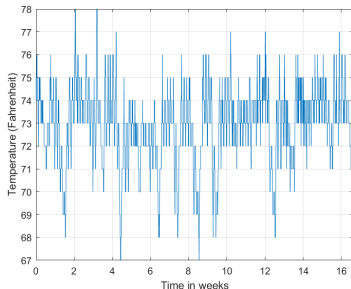
A measure of relevance/strength of a target frequency k

$$A_k = \text{Re}^2(X_k) + \text{Im}^2(X_k)$$



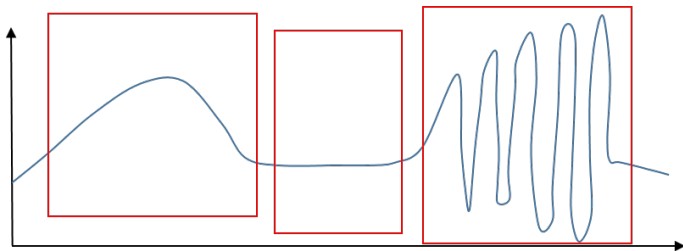
DFT in Action

- Use the DFT elements X_1, \dots, X_K as representation of the signal to train predictor/classifier
- Representation in spectral domain can reveal patterns that are not clear in time domain

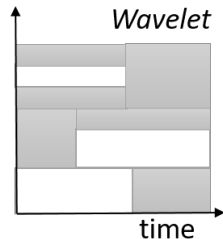
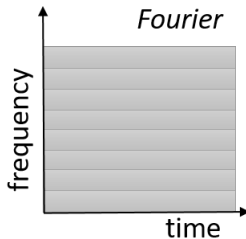
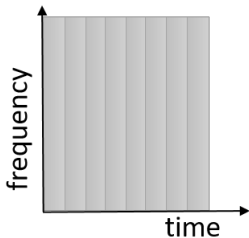


Limitations of DFT

Sometimes we might need localized frequencies rather than **global frequency analysis**



Graphical Intuition



Split signal in frequency bands only if they exist in specific time-intervals

Wavelets

Split the signal using an orthonormal basis generated by **translation and dilation** of a **mother wavelet**

$$f(\mathbf{x}) = \sum_{t \in \mathbb{Z}} \sum_{k \in \mathbb{Z}} \psi_{t,k}(\mathbf{x})$$

Terms k and t regulate scaling and shifting of the wavelet

$$\psi_{t,k}(\mathbf{x}) = 2^{k/2} \psi(2^k \mathbf{x} - t)$$

with respect to the mother $\psi(\cdot)$. E.g.

$k < 1$ Compresses the signal

$k > 1$ Dilates the signal

Many different possible choices for the mother wavelet function:
Haar, Daubechies, Gabor,...

Take Home Messages

- Old-school pattern recognition on timeseries is about **learning coefficients** that describe properties of the time series
 - Autoregressive coefficients (**time domain**)
 - Fourier coefficient (**frequency domain**)
- Often **linear methods**
 - **Autocorrelation** reveals similitude of a signal with delayed versions of itself
 - **Cross-correlation** provides hints on time series similarity and how to align them
- Fourier analysis allows to identify **recurring patterns** and to identify key frequencies in the signal

Next Lecture

- Introduction to image processing
- Representing images and visual content
- Identify informative parts of an image
- Spectral analysis in 2D